

Partial Differential Equations.

(1)

Introduction:-

Many physical problems in Science and engineering, when formulated mathematically give rise to partial differential equation (PDE). In order to understand the physical behaviour of the mathematical model, it is necessary to have some knowledge about the mathematical character, properties and the solution of the governing PDE.

An equation which involves several independent variables denoted by x, y, z, t, \dots a dependent function u of these variables and its partial derivatives with respect to the independent variables such as

$$F(x, y, z, t, \dots, u, u_x, u_y, u_z, u_t, \dots, u_{xx},$$

$u_{yy}, \dots, u_{xy}, \dots) = 0$ is called a partial differential equation.

Definition:-

The order of a partial differential equation is the order of the highest order partial derivative occurring in the equation.

Second order partial differential equation.

Sec 2.1 :-

Origin of second order partial differential equations.

Consider the function

$$z = f(u) + g(v) + w \rightarrow (1)$$

where f and g are functions of u and v respectively and u, v and w are functions of x and y .

Take the following to be satisfied,

$$p = \frac{\partial z}{\partial x}, q = \frac{\partial z}{\partial y}, r = \frac{\partial^2 z}{\partial x^2}, s = \frac{\partial^2 z}{\partial x \partial y} \text{ and}$$

$$t = \frac{\partial^2 z}{\partial y^2}$$

Differentiating (1) with respect to x ,

we get,

$$\frac{\partial z}{\partial x} = f'(u)u_x + g'(v)v_x + w_x$$

$$p = f'(u)u_x + g'(v)v_x + w_x \rightarrow (2)$$

Differentiating (1) with respect to y ,

we get $\frac{\partial z}{\partial y} = f'(u)u_y + g'(v)v_y + w_y$

$$q = f'(u)u_y + g'(v)v_y + w_y \rightarrow (3)$$

Differentiating (2) with respect to x ,

we get

(3)

$$\frac{\partial^2 z}{\partial x^2} = f''(u) u_{xx}^2 + f'(u) u_{xex} + g''(v) v_{xx}^2 + \\ g'(v) v_{xex} + \omega_{xex}$$

$$r = f''(u) u_{xx}^2 + f'(u) u_{xex} + g''(v) v_{xx}^2 + \\ g'(v) v_{xex} + \omega_{xex}$$

$\rightarrow (4)$

Differentiating (2) with respect to y,

we get

$$\frac{\partial^2 z}{\partial x \partial y} = f''(u) u_{xy} u_y + f'(u) u_{xy} + \\ g''(v) v_{xy} u_y + g'(v) v_{xy} + \omega_{xy}$$

$$S = f''(u) u_{xy} u_y + g''(v) v_{xy} u_y + f'(u) u_{xy} + \\ g'(v) v_{xy} + \omega_{xy} \rightarrow (5)$$

Differentiating (3) with respect to y we get

$$\frac{\partial^2 z}{\partial y^2} = f''(u) u_y^2 + f'(u) u_{yy} + g''(v) v_y^2 + \\ g'(v) v_{yy} + \omega_{yy}$$

$$I = f''(u) u_y^2 + f'(u) u_{yy} + g''(v) v_y^2 + \\ g'(v) v_{yy} + \omega_{yy} \rightarrow (6)$$

Now the above five equations contain four arbitrary quantities g' , f' , g'' and f'' .

Eliminating these quantities,

we get

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$$P - w_{xx} \quad u_{xy} \quad v_{yx} \quad 0 \quad 0 \quad | \quad (4)$$

$$q - w_y \quad u_y \quad v_y \quad 0 \quad 0$$

$$r - w_{xy} \quad u_{xx} \quad v_{yy} \quad u_x^2 \quad v_x^2 \quad = 0$$

$$s - w_{xy} \quad u_{xy} \quad v_{xy} \quad u_{yy} \quad v_{xy} \quad \rightarrow (4)$$

$$t - w_{yy} \quad u_{yy} \quad v_{yy} \quad u_y^2 \quad v_y^2$$

which involves only P, Q, R, S, T and known functions of x and y .

\therefore It is a partial differential equations of second order.

If we expand (4) in terms of first column, we get

$$R_y + S_x + T_z + P_p + Q_q = w \rightarrow (8)$$

where R, S, T, P, Q and w are known functions of x and y .

$\therefore z = f(u) + g(v) + w$ is a solution of the second order linear partial differential equation (8), which is a particular type of equation and contains dependent variable z .

Example 2.1.1 :-

If $u = f(x+iy) + g(x-iy)$ where f and g are arbitrary functions,

$$\text{show that } \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0.$$

Solution:-

(15)

$$\text{Given } u = f(x+iy) + g(x-iy)$$

To find $\frac{\partial u}{\partial x}$, $\frac{\partial^2 u}{\partial x^2}$, $\frac{\partial u}{\partial y}$ and $\frac{\partial^2 u}{\partial y^2}$

$$\text{Now } \frac{\partial u}{\partial x} = f'(x+iy) + g'(x-iy)$$

$$\frac{\partial^2 u}{\partial x^2} = f''(x+iy) + g''(x-iy) \rightarrow (1)$$

$$\frac{\partial u}{\partial y} = f'(x+iy)(i) + g'(x-iy)(-i)$$

$$\frac{\partial^2 u}{\partial y^2} = f''(x+iy)(i)(-i) + g''(x-iy)(-i)(-i)$$

$$\frac{\partial^2 u}{\partial y^2} = -f''(x+iy) - g''(x-iy) \rightarrow (2).$$

Adding (1) and (2), we get

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0$$

which is the required result.

Example 2.1.2 :-

If f and g are arbitrary functions of their respective arguments, show that

$$u = f(x - vt + idy) + g(x - vt - idy) \text{ is a}$$

$$\text{Solution of } \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{1}{c^2} \frac{\partial^2 u}{\partial t^2}$$

$$\text{Provided } x^2 = 1 - \frac{v^2}{c^2}.$$

Solution :-

(6)

$$\text{Given } u = f(x - vt + iy) + g(x - vt - iy) \rightarrow (1)$$

$$\text{To find } \frac{\partial^2 u}{\partial x^2}, \frac{\partial^2 u}{\partial y^2} \text{ and } \frac{\partial^2 u}{\partial t^2}$$

$$\text{Now } \frac{\partial u}{\partial x} = f'(x - vt + iy) + g'(x - vt - iy)$$

$$\frac{\partial^2 u}{\partial x^2} = f''(x - vt + iy) + g''(x - vt - iy) \rightarrow (2)$$

$$\frac{\partial u}{\partial y} = f'(x - vt + iy)(i\alpha) + g'(x - vt - iy)(-\alpha)$$

$$\frac{\partial^2 u}{\partial y^2} = f''(x - vt + iy)(i\alpha)(i\alpha) + g''(x - vt - iy)(-\alpha)(\alpha)$$

$$= -\alpha^2 f''(x - vt + iy) - \alpha^2 g''(x - vt - iy)$$

$$\frac{\partial^2 u}{\partial y^2} = -\alpha^2 [f''(x - vt + iy) + g''(x - vt - iy)] \rightarrow (3)$$

$$\frac{\partial u}{\partial t} = f'(x - vt + iy)(-v) + g'(x - vt - iy)(-v)$$

$$\frac{\partial^2 u}{\partial t^2} = f''(x - vt + iy)(-v)(-v) + g''(x - vt - iy)(-v)(-v)$$

$$\frac{\partial^2 u}{\partial t^2} = v^2 [f''(x - vt + iy) + g''(x - vt - iy)] \rightarrow (4)$$

Adding (2) and (3) we get

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = (1-\alpha^2) [f''(x-vt+iy) + g''(x-vt-iy)]$$

using (4) we get

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{(1-\alpha^2)}{v^2} \left(\frac{\partial^2 u}{\partial t^2} \right)$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{1}{c^2} \frac{\partial^2 u}{\partial t^2} \text{ where}$$

$c^2 = v^2/\alpha^2$ and $\alpha^2 = 1 - c^2$

$$\alpha^2 = 1 - \frac{c^2}{v^2}$$

Thus $u = f(x-vt+iy) + g(x-vt-iy)$ is

a solution of the given partial differential equation.

Section 2.2:

Linear Partial Differential Equations

with constant coefficients.

An equation of the form

$$F(D, D')z = f(x, y) \rightarrow (1)$$

where $F(D, D')$ is a differential

operator of the type

$$F(D, D') = \sum_{r=0}^m \sum_{s=0}^n C_{rs} D^r D' \rightarrow (2)$$

in which the coefficients C_{rs} are constants, $D = \frac{\partial}{\partial x}$ and $D' = \frac{\partial}{\partial y}$ is called a linear partial differential equation

with constant coefficients.

Solution:-

(8)

Any most general solution of the corresponding homogeneous linear partial differential equation $F(D, D')z = 0 \rightarrow (3)$ is called the complementary function of equation (1).

Similarly, any particular solution of (1) which contains no arbitrary constant or function is called a Particular integral of (1).

Thus the general solution of (1) is the sum of complementary function (CF) and particular integral (PI) of (1).

$$\text{Hence } z = C.F + P.I.$$

Theorem - 2.2.1 :-

If u_1, u_2, \dots, u_n are solutions of the homogeneous linear partial differential equation $F(D, D')z = 0$, then $\sum_{r=1}^n c_r u_r$ where c_r 's are arbitrary constants is also a solution.

Proof :-

Given u_1, u_2, \dots, u_n are solutions of the PDE $F(D, D')z = 0 \rightarrow (1)$.

To Prove $\sum_{r=1}^n c_r u_r$ is also a solution of (1)

Since u_1, u_2, \dots, u_n are solution of the PDE $\therefore F(D, D')z = 0$ we get (9)

$$F(D, D')u_r = 0 \rightarrow (2) \quad r=1, 2, \dots, n$$

Now $F(D, D')c_r u_r = c_r F(D, D')u_r$ and

$$F(D, D') \sum_{r=1}^n u_r = \sum_{r=1}^n F(D, D')u_r \text{ for}$$

any value of $r=1, 2, \dots, n$

any set of function u_r is allowed.

Therefore,

$$F(D, D') \sum_{r=1}^n c_r u_r = \sum_{r=1}^n F(D, D') (c_r u_r)$$

$$\therefore c_1 c_2 \dots c_n = 0 \Rightarrow \sum_{r=1}^n c_r F(D, D')u_r$$

$$\therefore F(D, D') \sum_{r=1}^n c_r u_r = 0 \quad (\text{by (2)})$$

From (1), we have $F(D, D')z = 0$

\therefore we get $z = \sum_{r=1}^n c_r u_r$ satisfies the given equation $F(D, D')z = 0$ and hence it is a solution of $F(D, D')z = 0$.

Hence the result.

Note :-

The operator $F(D, D') = 0$ is classified into two types :-

Reducible and Irreducible.

Reducible : -

The operator $F(D, D')$ is said to be reducible if it can be factorized into the linear factors of the type $D + aD' + b$ where a and b are constants.

Irreducible : -

The operator $F(D, D')$ is said to be irreducible if it is not reducible.

Example : -

Reducible : $F(D, D') = D^2 - D'^2$

$$= (D + D')(D - D')$$

Irreducible : $F(D, D') = D^2 + D'^2$

Theorem 2.2.2 : -

If $\alpha_r, \beta_r, \alpha'_r, \beta'_r$ are factors of $F(D, D')$ and $\phi_r(y)$ is an arbitrary function of the single variable y then $u_r = e^{\left(\frac{-\beta_r y}{\alpha_r}\right)} \phi_r(\beta_r \alpha_r - \alpha'_r y)$ for $\alpha_r \neq 0$

is a solution of $F(D, D')z = 0$.

Proof : -

Given equation is $F(D, D')z = 0 \rightarrow (1)$

To Prove

$$u_r = e^{\left(\frac{-\beta_r y}{\alpha_r}\right)} \phi_r(\beta_r \alpha_r - \alpha'_r y) \text{ is a}$$

Solution of (1). $\rightarrow (2)$

Differentiating (2) partially with (1)

Respect to x , we get

$$\frac{\partial}{\partial x} u_r = - \frac{\gamma_r}{\alpha_r} e^{-\frac{\gamma_r x}{\alpha_r}} \phi'_r (\beta_r x - \alpha_r y) +$$

$$e^{\left(-\frac{\gamma_r x}{\alpha_r}\right)} \cdot \phi'_r (\beta_r x - \alpha_r y) \beta_r$$

$$D u_r = - \frac{\gamma_r}{\alpha_r} u_r + \beta_r \cdot e^{-\frac{\gamma_r x}{\alpha_r}} \phi'_r (\beta_r x - \alpha_r y) \rightarrow (3)$$

Differentiating (2) partially with respect

to y , we get

$$\frac{\partial}{\partial y} u_r = e^{\left(-\frac{\gamma_r x}{\alpha_r}\right)} \phi'_r (\beta_r x - \alpha_r y) (-\alpha_r)$$

$$D' u_r = -\alpha_r e^{-\frac{\gamma_r x}{\alpha_r}} \phi'_r (\beta_r x - \alpha_r y) \rightarrow (4)$$

Now From (3),

$$\alpha_r D u_r = -\gamma_r u_r + \alpha_r \beta_r e^{-\frac{\gamma_r x}{\alpha_r}} \phi'_r (\beta_r x - \alpha_r y) \rightarrow (5)$$

$$\beta_r D' u_r = -\beta_r \alpha_r e^{-\frac{\gamma_r x}{\alpha_r}} \phi'_r (\beta_r x - \alpha_r y) \rightarrow (6)$$

Adding (5) and (6) we get

$$\alpha_r D u_r + \beta_r D' u_r = -\gamma_r u_r$$

$$\Rightarrow (\alpha_r D + \beta_r D' + \gamma_r) u_r = 0 \rightarrow (7)$$

Now

$$F(D, D') \cdot u_r = \prod_{s=1}^n (\alpha_s D + \beta_s D' + \gamma_s)$$

$$s \neq r \quad (\alpha_r D + \beta_r D' + \gamma_r) u_r$$

$$\rightarrow (8)$$

Combining (7) and (8) we get

$$F(D, D') u_r = 0$$

$$\text{Thus } u_r = e^{-\frac{\gamma_r x}{\alpha_r}} \psi_r (\beta_r x - \alpha_r y) \text{ is}$$

a solution of $F(D, D') z = 0$.

Definition:-

A Partial differential equation $F(D, D') z = f(x, y)$ is said to be reducible if $F(D, D')$ can be written as a product of linear factors in D and D' .

$$F(D, D') = \prod_{r=1}^n (\alpha_r D + \beta_r D' + \gamma_r).$$

Definition:-

Equations which are not reducible are called irreducible equations.

Section 2.3:-

Method of Solving linear Partial differential Equation.

2.3.1. Solution of Reducible Equations:-

Let $F(D, D')z = f(x, y) \rightarrow (1)$ (13)

be a partial differential equation.

Since equation (1) is reducible,
we can write

$$F(D, D')z = \sum_{r=1}^n (\alpha_r D + \beta_r D' + \gamma_r) z \rightarrow (2)$$

If z satisfies $(\alpha_r D + \beta_r D' + \gamma_r)z = 0$,
 $r = 0, 1, 2, \dots, n$, then it gives

complementary function.

Now $(\alpha_r D + \beta_r D' + \gamma_r)z = 0$ is a
linear first order PDE.

$\alpha_r \frac{\partial z}{\partial x} + \beta_r \frac{\partial z}{\partial y} + \gamma_r z = 0$ is a linear

first order partial differential equation

$$\therefore \frac{dx}{\alpha_r} = \frac{dy}{\beta_r} = \frac{dz}{-\gamma_r z} \rightarrow (3)$$

From first two members, we get

$$\frac{dx}{\alpha_r} = \frac{dy}{\beta_r}$$

$$\Rightarrow \frac{x}{\alpha_r} = \frac{y}{\beta_r} + C_r$$

$$\Rightarrow \beta_r x - \alpha_r y = c_r \rightarrow (4) c_r \text{ is}$$

constant.

Also,

$$\frac{dx}{\alpha_r} = - \frac{dz}{\beta_r z} \quad (14)$$

$$\Rightarrow \frac{1}{z} \frac{dz}{dx} = - \frac{\beta_r}{\alpha_r}$$

$$\Rightarrow \frac{dz}{z} = - \frac{\beta_r}{\alpha_r} dx$$

Integrating, on both sides, we get

$$\log z = - \frac{\beta_r}{\alpha_r} x + \text{constant}$$

$$z = A_r e^{\left(-\frac{\beta_r}{\alpha_r}\right)x} \quad \text{where } A_r \text{ is a constant.}$$

$$\therefore z = \phi_r(x_r) e^{\left(-\frac{\beta_r}{\alpha_r}\right)x}$$

$$z = \phi_r(\beta_r x - \alpha_r y) e^{\left(-\frac{\beta_r}{\alpha_r}\right)x} \quad [\text{using (4)}]$$

If $\alpha_r \neq 0$, then

$$CF = \sum_{r=1}^n \phi_r (\beta_r x - \alpha_r y) e^{\left(-\frac{\beta_r x}{\alpha_r}\right)}$$

ϕ_r is an arbitrary function.

Particular Case :-

If $\alpha_r = 0$, then from (3), we get

$$\beta_r x = \text{constant} \approx C_r \quad (\text{say})$$

∴ (5)

Also from (3), we have

$$\frac{dy}{\beta_r} = - \frac{dz}{\beta_r z}$$

$$-\frac{\gamma_r}{B_r} dy = \frac{dz}{z} \quad (15)$$

Integrating on both sides, we get

$$\begin{aligned} -\frac{\gamma_r}{B_r} y + (\text{constant}) &= \log z \\ \Rightarrow z &= \phi_r(c_r) \cdot e^{(-\frac{\gamma_r}{B_r} y)} \\ z &= \phi_r(B_r x) e^{(-\frac{\gamma_r}{B_r} y)} \quad [\text{using (15)}] \end{aligned}$$

In this case,

$$CF = \sum_{r=1}^n \phi_r(B_r x) e^{(-\frac{\gamma_r}{B_r} y)}$$

The above two cases are applicable, when there is no repeated factor of the type $(\alpha_r D + \beta_r D' + \gamma_r)$.

Solution for the case of Repeated factors:

Let the partial differential equation $F(D, D') z = f(x, y)$ has repeated factors.

Suppose that $(\alpha_r D + \beta_r D' + \gamma_r)^2$ is a factor of $F(D, D')$.

Then we have

$$(\alpha_r D + \beta_r D' + \gamma_r)^2 z = 0 \rightarrow (16)$$

(or) $(\alpha_r D + \beta_r D' + \gamma_r) z_1 = z$, where

$$(\alpha_r D + \beta_r D' + \gamma_r) z_1 = 0.$$

$$\therefore z_r = \phi_r (\beta_r x + \alpha_r y) e^{-\frac{\gamma_r x}{\alpha_r}} \xrightarrow{(16)} \rightarrow (7)$$

we have

$$\begin{aligned}
 & (\alpha_r D + \beta_r D' + \gamma_r) z = z_r \\
 & = \phi_r (\beta_r x - \alpha_r y) e^{-\frac{\gamma_r x}{\alpha_r}} \\
 \Rightarrow & (\alpha_r D + \beta_r D') z = e^{-\frac{\gamma_r x}{\alpha_r}} \phi_r (\beta_r x - \alpha_r y) - \gamma_r z \\
 & \alpha_r \frac{\partial z}{\partial x} + \beta_r \frac{\partial z}{\partial y} = e^{-\frac{\gamma_r x}{\alpha_r}} \phi_r (\beta_r x - \alpha_r y) - \gamma_r z
 \end{aligned}$$

Taking the first two members, we get

also

$$\begin{aligned}
 \therefore \frac{dx}{\alpha_r} &= \frac{dy}{\beta_r} = \frac{dz}{e^{-\frac{\gamma_r x}{\alpha_r}} \phi_r (\beta_r x - \alpha_r y) - \gamma_r z}
 \end{aligned}$$

Taking the first two members, we get

$$\frac{dx}{\alpha_r} = \frac{dy}{\beta_r}$$

$$\Rightarrow \partial \beta_r \oplus \alpha_r y = c_r, \quad c_r \text{ being a constant}$$

Also, taking the first and the third members, we get

$$\frac{dx}{\alpha_r} = \frac{dz}{e^{-\frac{\gamma_r x}{\alpha_r}} \phi_r (\beta_r x - \alpha_r y) - \gamma_r z}$$

$$\Rightarrow \frac{dz}{dx} = \frac{e^{-\frac{\gamma_r x}{\alpha_r}} \phi_r (\beta_r x - \alpha_r y) - \gamma_r z}{\alpha_r}$$

$$\frac{dz}{dx} = -\frac{\beta_r z}{\alpha_r} + \frac{1}{\alpha_r} e^{-\left(\frac{\beta_r x}{\alpha_r}\right)} \psi_r(\beta_r x - \alpha_r y) \quad (14)$$

$$\Rightarrow \frac{dz}{dx} + \frac{\beta_r}{\alpha_r} z = \frac{1}{\alpha_r} e^{-\left(\frac{\beta_r x}{\alpha_r}\right)} \psi_r(c_r)$$

This is a linear ordinary differential equation, whose integrating factor is given by $IF = e^{\int \frac{\beta_r}{\alpha_r} dx}$

$$IF = e^{\frac{\beta_r x}{\alpha_r}}$$

Therefore, its solution is given by

$$ze^{\frac{\beta_r x}{\alpha_r}} = \int \frac{1}{\alpha_r} e^{\frac{\beta_r x}{\alpha_r}} \psi_r(c_r) dx$$

$$ze^{\frac{\beta_r x}{\alpha_r}} = \frac{x}{\alpha_r} \psi_r(c_r) + \psi_r(c_r)$$

$$\Rightarrow z = e^{-\frac{\beta_r x}{\alpha_r}} \left[x \psi_r(\beta_r x - \alpha_r y) + \psi_r(\beta_r x - \alpha_r y) \right]$$

This procedure can be generalized up to any order of repetition of factors. Adding this to the sum of the other solutions corresponding to the linear factors without repetition, we get the required complementary function.

2.3.2 :- (12)

Solution of irreducible Equations with
constant coefficients:-

$$\text{Let } F(D, D')z = f(x, y) \rightarrow (1)$$

be an irreducible linear partial

differential equation with constant

coefficients.

Let $F(D, D') = F_1(D, D')F_2(D, D')$ where
 F_2 is reducible and F_1 is irreducible.

Since $F_2(D, D')$ is reducible, we
get the solutions corresponding to linear
factors of $F_2(D, D')$ will be of the type

$$e^{\frac{-\beta_r x}{\alpha_r}} \phi_r(\beta_r x - \alpha_r y) \text{ if } \alpha_r \neq 0$$

and

$$e^{\frac{-\beta_r x}{\alpha_r}} \phi_r(\beta_r x) \text{ if } \alpha_r \neq 0$$

To find the solutions corresponding
to the irreducible factor of $F_1(D, D')$.

We suppose that $z = e^{ax+by}$
is a solution of $F_1(D, D')z = 0$ and a, b are constants.

$$\therefore F_1(D, D')e^{ax+by} = F(a, b)e^{ax+by}$$

must vanish and hence we get the

Condition $F(a, b) = 0$ [since $a^a e^{ax+by} \neq 0$].

$$\therefore z = \sum_r c_r e^{a_r x + b_r y} \quad (1a)$$

$F_r(a_r, b_r) = 0, r=1, 2, \dots$ is a complementary function corresponding to the irreducible factors.

The arbitrary constants a_r and b_r can be chosen depending upon the given conditions.

2. 3. 3' :-

Rules for finding complementary function:-

Consider the equation

$$\frac{\partial^2 z}{\partial x^2} + a_1 \frac{\partial^2 z}{\partial x \partial y} + a_2 \frac{\partial^2 z}{\partial y^2} = 0$$

This can be written as

$$(D^2 + a_1 D D' + a_2 D'^2) z = 0 \rightarrow (1)$$

where $D = \frac{\partial}{\partial x}$ and $D' = \frac{\partial}{\partial y}$

Then the Auxiliary equation is

$$m^2 + a_1 m + a_2 = 0 \rightarrow (2), m = D/D'$$

Let m_1 and m_2 be the roots of (2)

Case - I :-

When $m_1 \neq m_2$

Then the equation (1) can be written as

$$(D - m_1 D') (D - m_2 D') z = 0 \rightarrow (3)$$

(20)

Now the solution of $(D - m_2 D') z = 0$
will also be a solution of eqn (3).

$$\text{But } (D - m_2 D') z = 0$$

$$\Rightarrow P - m_2 Q = 0$$

This is of diag. form

and the Auxillary equations are

$$\frac{dx}{1} = \frac{dy}{-m_2} = \frac{dz}{0}$$

Consider the first two members, we get

$$\frac{dx}{1} = \frac{dy}{-m_2}$$

$$\Rightarrow dy + m_2 dx = 0$$

$$y + m_2 x = c_1$$

Also,

$$\frac{dx}{1} = \frac{dz}{0}$$

$$\Rightarrow dz = 0$$

$$\Rightarrow z = c_2$$

$\therefore z = f_2(y + m_2 x)$ is a solution of
 $(D - m_2 D') z = 0$ where f_2 is
an arbitrary function of its arguments.

Similarly eqn (3) will also be
satisfied by the solution of $(D - m_1 D') = 0$
by $z = f_1(y + m_1 x)$ when f_1 is another
arbitrary function.

Hence the complete solution of (1) is

$$z = f_1(y + mx, \alpha) + f_2(y + m_2x). \quad (2)$$

Case-II :-

when two roots are equal

$$m_1 = m_2 = m \text{ (say)}$$

then eqn (1) can be written as

$$(D - mD')^2 z = 0 \rightarrow (4)$$

$$\text{Let } (D - mD')z = u.$$

Equation (4) becomes

$$(D - mD')u = 0$$

Then by case I, its solution is

$$u = f(y + mx).$$

∴ (D - mD')z = u takes the form

$$(D - mD')z = f(y + mx)$$

$$\Rightarrow D - mq = f(y + mx)$$

$$\Rightarrow \frac{dx}{1} = \frac{dy}{-m} = \frac{dz}{f(y + mx)}$$

From the first two members, we get

$$\frac{dx}{1} = \frac{dy}{-m}$$

$$\Rightarrow dy + m dx = 0$$

$$\Rightarrow y + mx = c,$$

$$\Rightarrow dz = f(c_1) dx$$

$$\Rightarrow z = xf(c_1) + c_2$$

$$\Rightarrow z = xf(y + mx) + c_2$$

Thus the complete solution of (1) is
$$z = f_1(y + m_1x) + \alpha f_2(y + m_2x). \quad (2)$$

Note:-

Generalizing the results of case I and case II.

1) If the roots of AE are m_1, m_2, \dots call distinct, then

$$CF = f_1(y + m_1x) + f_2(y + m_2x) + \dots$$

where f_1, f_2, \dots are all arbitrary function.

2) If two roots of AE are equal.

$$m_1 = m_2 \text{ then}$$

$$CF = f_1(y + m_1x) + \alpha f_2(y + m_1x) + f_3(y + m_3x) + \dots$$

where f_1, f_2, \dots are all arbitrary function.

3) If three roots of AE are equal.

$$m_1 = m_2 = m_3 \text{ then}$$

$$CF = f_1(y + m_1x) + \alpha f_2(y + m_1x) + \alpha^2 f_3(y + m_1x) + f_4(y + m_4x) + \dots$$

2.3.4:-

Rules for finding particular integral.

See book.

Example : 2. 3. 1 : - (23)

v) Solve the equation

$$\frac{\partial^3 z}{\partial x^3} - 2 \frac{\partial^3 z}{\partial x^2 \partial y} - \frac{\partial^3 z}{\partial x \partial y^2} + 2 \frac{\partial^3 z}{\partial y^3} = e^{x+y}$$

Solution : -

Given equation can be written as

$$(D^3 - 2D^2 D' - DD'^2 + 2D'^3)z = e^{x+y}$$

$$F(D, D') = D^3 - 2D^2 D' - DD'^2 + 2D'^3$$

The auxiliary equation is

$$m^3 - 2m^2 - m + 2 = 0 \quad \text{where } m = \frac{D}{D'}$$

$$(m-1)(m+1)(m-2)=0$$

The roots are $m=1$, $m=-1$, $m=2$

$$\therefore c_1 = \phi_1(y-x) + \phi_2(y+x) + \phi_3(y+2x) \rightarrow (1)$$

Particular integral ,

$$\begin{aligned} PI &= \frac{1}{(D-D')(D+D')(D-2D')} e^{x+y} \\ &= \frac{1}{(D-D')} \left[\frac{1}{(1+1)(1-2)} \right] e^{x+y} \end{aligned}$$

$$PI = \frac{1}{2} \frac{-1}{(D-D')} e^{x+y} \rightarrow (2)$$

$$\text{Let } w = \frac{1}{(D-D')} e^{x+y}$$

$$\Rightarrow (D - D')w = e^{2x+y} \quad (24)$$

$$\therefore \frac{dx}{1} = \frac{dy}{-1} = \frac{dw}{e^{2x+y}}$$

From first two members,

$$\frac{dx}{1} = \frac{dy}{-1}$$

$$\Rightarrow dx + dy = 0$$

$$\Rightarrow x + y = c$$

$$\text{Also } \frac{dx}{1} = \frac{dw}{e^{2x+y}}$$

$$\Rightarrow \frac{dw}{e^c} = \frac{dx}{1}$$

$$\Rightarrow dw = e^c dx$$

$$\Rightarrow w = e^c x$$

$$w = xe^{2x+y} \rightarrow (3)$$

Using (3) in (2) we get

$$PI = -\frac{1}{2} xe^{2x+y} \rightarrow (4)$$

From (1) and (4) we get

The complete solution is

$$Z = \phi_1(y-x) + \phi_2(y+x) + \phi_3(y+2x) \\ - \frac{1}{2} xe^{2x+y}$$

Example - 2 & 3 :-

Refer book.

classification of second order partial differential equation.

Definition :-

A second order partial differential equation which is linear with respect to the second order partial derivatives r, s and t is said to be a quasi-linear PDE of second order.

Example :-

The equation $R_r + S_s + T_t + f(x, y, z, p, q) = 0$, where $f(x, y, z, p, q)$ need not be linear, is a quasi-linear PDE.

Note :-

The coefficients R, S, T may be functions of x and y . However, for the sake of simplicity we assume them to be constants.

Definition :-

The equation $R_r + S_s + T_t + f(x, y, z, p, q) = 0$ is said to be

- i) Elliptic if $S^2 - 4RT < 0$
- ii) parabolic if $S^2 - 4RT = 0$ and
- iii) Hyperbolic if $S^2 - 4RT > 0$ at a point (x_0, y_0) .

If this is true at all the points in

a domain Ω , then the equation (1) is said to be elliptic, parabolic (or) ⁽²⁶⁾ hyperbolic in that domain.

2.4.1: Canonical Forms:-

Reduce the PDE

$R_r + S_g + T_f + f(x, y, z; p, q) = 0$ to a canonical form.

In order to reduce the PDE

$R_r + S_g + T_f + f(x, y, z, p, q) = 0 \rightarrow (1)$

to a canonical form, we apply the transformation $\xi = \xi(x, y)$, $\eta = \eta(x, y) \rightarrow (2)$

Here the functions ξ and η are continuously differentiable and the

Jacobian

$$J = \frac{\partial(\xi, \eta)}{\partial(x, y)} = \begin{vmatrix} \xi_x & \xi_y \\ \eta_x & \eta_y \end{vmatrix}$$

$$J = \xi_x \eta_y - \xi_y \eta_x \neq 0 \rightarrow (3)$$

in the domain Ω where equation (1) holds. Now we have

$$p = \frac{\partial z}{\partial x} = \frac{\partial z}{\partial \xi} \frac{\partial \xi}{\partial x} + \frac{\partial z}{\partial \eta} \frac{\partial \eta}{\partial x}$$

$$p = z_{\xi} \xi_x + z_{\eta} \eta_x$$

$$q = z_4 \cdot 4_y + z_n \cdot n_y \quad (27)$$

$$r = \frac{\partial^2 z}{\partial x^2}$$

$$r = \frac{\partial^2 z}{\partial x^2} = \frac{\partial}{\partial x} [z_4 \cdot 4_x + z_n \cdot n_x]$$

$$= z_{44} \cdot 4_x^2 + z_{nn} \cdot n_x^2 + z_4 \cdot 4_{xx} +$$

$$z_{nn} \cdot n_x \cdot n_x + z_{n4} \cdot 4_x \cdot n_x + z_n \cdot n_{xx}$$

$$r = z_{44} \cdot 4_x^2 + z_{nn} \cdot n_x^2 + z_4 \cdot 4_{xx} + z_n \cdot n_{xx}$$

$$+ 2 z_{4n} \cdot 4_x \cdot n_x$$

11) $\frac{dy}{dx}$

$$t = \frac{\partial^2 z}{\partial y^2} = z_{44} \cdot 4_y^2 + z_{nn} \cdot n_y^2 + z_4 \cdot 4_{yy} +$$

$$z_n \cdot n_{yy} + 2 z_{4n} \cdot 4_y \cdot n_y$$

$$S = \frac{\partial^2 z}{\partial x \partial y} = z_{44} \cdot 4_x \cdot 4_y + z_{nn} \cdot n_x \cdot n_y +$$

$$z_{4n} \cdot 4_x \cdot n_y + z_{4n} \cdot n_x \cdot 4_y +$$

$$z_n \cdot n_x \cdot n_y + z_4 \cdot 4_{xy} \cdot 4_y$$

$$= z_{44} \cdot 4_x \cdot 4_y + z_{nn} \cdot n_x \cdot n_y + z_{4n}$$

$$[4_x \cdot n_y + n_x \cdot 4_y] + z_n \cdot n_x \cdot n_y +$$

$$z_4 \cdot 4_{xy} \cdot 4_y$$

Substituting these values

P, q, r, s and t in (1) we get

$$R \left[Z_{44} \cdot 4_{\eta_x}^2 + Z_{nn} \eta_x^2 + Z_4 4_{\eta_{xx}} + Z_n \eta_{xx} + \dots \right] + \dots \quad (28)$$

$$+ 2 Z_{4\eta} (4_{\eta_x} \eta_x) \left] + S \left[Z_{44} 4_{\eta_x} 4_{\eta_y} + Z_{nn} \eta_x \eta_y + \dots \right] + \dots \right]$$

$$+ Z_{4n} (4_{\eta_x} \eta_y + 4_{\eta_y} \eta_x) + Z_4 4_{\eta_{xy}} + Z_n + \eta_{xy} + \dots \right]$$

$$+ T \left[Z_{44} \cdot 4_{\eta_y}^2 + Z_{nn} \eta_y^2 + Z_4 4_{\eta_{yy}} + Z_n \eta_{yy} + \dots \right] + \dots$$

$$+ 2 Z_{4\eta} 4_{\eta_y} \eta_y \left] + f \left[\alpha, y, z, Z_4 4_{\eta_x} + Z_n \eta_x, \dots \right] \right]$$

$$+ Z_4 4_{\eta_y} + Z_n \eta_y \left] = 0 \right.$$

$$\Rightarrow Z_{44} \left[R 4_{\eta_x}^2 + S 4_{\eta_x} 4_{\eta_y} + T 4_{\eta_y}^2 \right] + \dots$$

$$+ Z_{44} \left[2R 4_{\eta_x} \eta_x + S (4_{\eta_x} \eta_y + 4_{\eta_y} \eta_x) + 2T 4_{\eta_y} \eta_y \right] + \dots$$

$$+ Z_{nn} \left[R \eta_x^2 + S \eta_x \eta_y + T \eta_y^2 \right] = F(4, \eta, z, Z_4, Z_n)$$

$$A(4_{\eta_x}, 4_{\eta_y}) Z_{44} + B(4_{\eta_x}, 4_{\eta_y}, \eta_x, \eta_y) E_{44}$$

$$+ A(\eta_x, \eta_y) Z_{nn} = f(4, \eta, z, Z_4, Z_n)$$

→ (4)

when,

$$A(4_{\eta_x}, 4_{\eta_y}) = A(u, v) = R u^2 + S u v + T v^2$$

$$B(4_{\eta_x}, 4_{\eta_y}, \eta_x, \eta_y) = B(u_1, v, u_2, v_2)$$

$$= 2R u_1 u_2 + S (u_1 v_2 + u_2 v_1) + 2T v_1 v_2$$

$$A(\eta_x, \eta_y) = R\eta_x^2 + S\eta_x\eta_y + T\eta_y^2$$

To find $B^2 - 4A(\eta_x, \eta_y) A(\eta_x, \eta_y)$ (2a)

$$B^2 - 4A(\eta_x, \eta_y) A(\eta_x, \eta_y)$$

$$B^2 - 4A(\eta_x, \eta_y) A(\eta_x, \eta_y) = [2Ru_1u_2 +$$

$$S(u_1v_2 + u_2v_1) + 2Tv_1v_2]^2 - 4[R\eta_x^2 + \\ S\eta_x\eta_y + T\eta_y^2](R\eta_x^2 + S\eta_x\eta_y + T\eta_y^2)$$

$$= 4R^2u_1^2u_2^2 + S^2(u_1v_2 + u_2v_1)^2 + 4T^2v_1^2v_2^2 \\ + 4RSu_1u_2(u_1v_2 + u_2v_1) + 4ST(u_1v_2 + u_2v_1)v_1v_2 \\ + [8RTu_1u_2v_1v_2] - 4[R^2\eta_x^2\eta_x^2 + \\ R^2\eta_x^2\eta_y^2 + RT\eta_x^2\eta_y^2 + SR\eta_x^2\eta_y^2\eta_x^2 + \\ S^2\eta_x^2\eta_y^2\eta_x^2\eta_y^2 + ST\eta_x^2\eta_y^2\eta_y^2 + RT\eta_y^2\eta_x^2 \\ + TS\eta_x^2\eta_y^2\eta_y^2 + T^2\eta_y^2\eta_y^2]$$

$$\Rightarrow B^2 - 4A(\eta_x, \eta_y) A(\eta_x, \eta_y) = (S^2 - 4RT)\Gamma$$

where Γ is $\eta_x\eta_y - \eta_x\eta_y\eta_x\eta_y$ (5)

Case-I:-

$$S^2 - 4RT > 0$$

Under the condition $S^2 - 4RT > 0$ the equation $R\lambda^2 + S\lambda + T = 0$ has real and distinct roots.

Let these roots be λ_1 and λ_2 .

Now, choose ψ and η such that

$$\psi_x = \lambda_1 \psi_y, \quad \eta_x = \lambda_2 \eta_y \rightarrow (6)$$

Now $\psi_x = \lambda_1 \psi_y \Rightarrow \psi_x - \lambda_1 \psi_y = 0$ being a first order linear PDE, we have

$$\frac{d\psi}{dx} = \frac{dy}{dx} = \frac{d\psi}{0}$$

$$\text{From } \frac{d\psi}{dx} = \frac{d\psi}{0} \Rightarrow d\psi = 0 \\ \Rightarrow \psi = \text{constant}$$

$$\text{Also, } \frac{d\psi}{dx} = \frac{dy}{-\lambda_1} \\ \Rightarrow \frac{dy}{dx} = -\lambda_1$$

$$\Rightarrow \frac{dy}{dx} + \lambda_1(x, y) = 0 \rightarrow (7)$$

$$\text{If we get } \frac{dy}{dx} + \lambda_2(x, y) = 0 \rightarrow (8).$$

(3) Let the solutions of these equations

(7) and (8) be given by

$$f_1(x, y) = \text{constant and}$$

$$f_2(x, y) = \text{constant.}$$

Thus we get $f_1(x, y) = \psi$ and $f_2(x, y) = \eta$ $\rightarrow (9)$.

$$\text{Now } A(\psi_{2x}, \psi_y) = R \psi_{2x}^2 + S \psi_{2x} \psi_y + T \psi_y^2 \quad (31)$$

$$= \psi_y^2 \left[R \frac{\psi_{2x}^2}{\psi_y^2} + S \frac{\psi_{2x} \psi_y}{\psi_y^2} + T \right]$$

$$= \psi_y^2 [R \lambda_1^2 + S \lambda_1 + T]$$

Since λ_1 is a root of the equation

$$R \lambda^2 + S \lambda + T = 0, \text{ we get}$$

$$R \lambda_1^2 + S \lambda_1 + T = 0$$

$$\therefore A(\psi_{2x}, \psi_y) = \psi_y^2 (c) = 0$$

II^{dy} Since λ_2 is a root of the equation

$$R \lambda^2 + S \lambda + T = 0, \text{ we get}$$

$$A(\psi_{2x}, \psi_y) = 0$$

\therefore Equation (5) is

$$B^2 = (S^2 - 4RT) J \neq 0$$

Then equation (4) reduces to

$$B(\psi_{2x}, \psi_y, \psi_{2x}, \psi_y) Z_{4n} = f(\psi, \eta, z, Z_4, Z_n)$$

$$Z_{4n} = g(\psi, \eta, z, Z_4, Z_n)$$

which is a required canonical form

for the hyperbolic partial differential

equation.

Case-II :- (32)

$$S^2 - 4RT = 0$$

Then the equation $R\lambda^2 + S\lambda + T = 0$ has equal roots $\lambda_1 = \lambda_2 = \lambda$ (say)

We choose $\psi = f_1(x, y)$

$f_1(x, y) = \text{constant}$ is a solution of

$$\frac{dy}{dx} + \lambda(x, y) = 0$$

Since $A(\psi_x, \psi_y) = 0$ and $S^2 - 4RT = 0$,

Equation (5) becomes,

$$B^2 = 0 \Rightarrow B = 0$$

However $A(\eta_x, \eta_y) \neq 0$, otherwise η will depend upon ψ .

Now using $A(\psi_x, \psi_y) = 0$ and $B = 0$ in equation (4) we get

$$A(\eta_x, \eta_y) z_{\eta\eta} = F(\psi, \eta, z, z_\psi, z_\eta)$$

$$\therefore z_{\eta\eta} = g(\psi, \eta, z, z_\psi, z_\eta)$$

which is the required canonical form for the parabolic partial differential equation.

Case-III:-

$$S^2 - 4RT < 0$$

In this case the roots of $R\lambda^2 + S\lambda + T = 0$
 are imaginary and therefore λ_1 and λ_2
 will be complex.

Let $\lambda_1 = \alpha + i\beta$, $\lambda_2 = \alpha - i\beta$, α, β are real.

$$\therefore \alpha = \frac{1}{2}(\lambda_1 + \lambda_2), \quad \beta = \frac{i}{2}(\lambda_2 - \lambda_1)$$

Now,

$$Z_{\lambda_1} = Z_\alpha \alpha_{\lambda_1} + Z_\beta \beta_{\lambda_1}$$

$$= Z_\alpha \frac{1}{2} + Z_\beta \left(\frac{i}{2} \right)$$

$$Z_{\lambda_1} = \frac{1}{2} Z_\alpha - \frac{i}{2} Z_\beta$$

$$Z_{\lambda_1 \lambda_2} = \frac{1}{2} [Z_{\alpha \alpha} \alpha_{\lambda_2} + Z_{\alpha \beta} \beta_{\lambda_2}] - \frac{i}{2}$$

$$[Z_{\beta \alpha} \alpha_{\lambda_2} + Z_{\beta \beta} \beta_{\lambda_2}]$$

$$= \frac{1}{2} [Z_{\alpha \alpha} \frac{1}{2} + Z_{\alpha \beta} \frac{i}{2}] - \frac{i}{2}$$

$$[Z_{\beta \alpha} \frac{1}{2} + Z_{\beta \beta} \frac{i}{2}]$$

$$= \frac{1}{4} Z_{\alpha \alpha} + \frac{i}{4} Z_{\alpha \beta} - \frac{i}{4} Z_{\beta \alpha} + \frac{1}{4} Z_{\beta \beta}$$

$$Z_{\lambda_1 \lambda_2} = \frac{1}{4} [Z_{\alpha \alpha} + Z_{\beta \beta}]$$

The desired canonical form a

$$Z_{\alpha \alpha} + Z_{\beta \beta} = \psi(\alpha, \beta, z, Z_\alpha, Z_\beta)$$

which is the required canonical

form for the elliptic PDE. (34)

Example - 2.4. 1 :-

Reduce the PDE

$$y^2 \frac{\partial^2 z}{\partial x^2} - 2xy \frac{\partial^2 z}{\partial x \partial y} + x^2 \frac{\partial^2 z}{\partial y^2} = \frac{y^2}{x} \frac{\partial z}{\partial x} + \frac{x^2}{y} \frac{\partial z}{\partial y}$$

do canonical form and hence solve it.

Solution :-

Given equation is

$$y^2 \frac{\partial^2 z}{\partial x^2} - 2xy \frac{\partial^2 z}{\partial x \partial y} + x^2 \frac{\partial^2 z}{\partial y^2} = \frac{y^2}{x} \frac{\partial z}{\partial x} + \frac{x^2}{y} \frac{\partial z}{\partial y}$$

$$\rightarrow \frac{\partial^2 z}{\partial x^2} - \frac{2xy}{y^2} \frac{\partial^2 z}{\partial x \partial y} + \frac{x^2}{y^2} \frac{\partial^2 z}{\partial y^2} = \frac{1}{x} \frac{\partial z}{\partial x} + \frac{x}{y} \frac{\partial z}{\partial y} \quad \rightarrow (1)$$

Here, $R = y^2$, $S = -2xy$, $T = x^2$

$$\text{Now } S^2 - 4RT = 4x^2 y^2 - 4x^2 y^2 = 0.$$

∴ The given equation (1) is a parabolic equation.

$$\text{Now } R\lambda^2 + S\lambda + T = 0$$

$$\Rightarrow y^2 \lambda^2 - 2xy \lambda + x^2 = 0$$

$$\Rightarrow (y\lambda - x)^2 = 0$$

$$\Rightarrow \lambda = x/y$$

$$\therefore \text{we have } \frac{dy}{dx} + \lambda(x, y) = 0$$

$$\Rightarrow \frac{dy}{dx} + \frac{x}{y} = 0$$

$$\Rightarrow \frac{dy}{dx} = -\frac{x}{y}$$

$$\text{Integrating } \Rightarrow x dx + y dy = 0$$

$$\Rightarrow x^2 + y^2 = \text{constant} \quad (35)$$

Let $\psi = x^2 + y^2$
 Since η is also be taken in such a way that it must be independent of ψ , hence we take $\eta = x^2 - y^2$

$$\psi_x = 2x, \psi_y = 2y, \eta_x = 2x, \eta_y = -2y$$

Now

$$z_x = z_{\psi} \psi_x + z_{\eta} \eta_x$$

$$= z_{\psi} (2x) + z_{\eta} (2x)$$

$$z_x = 2x (z_{\psi} + z_{\eta}) \rightarrow (2)$$

$$z_y = z_{\psi} \psi_y + z_{\eta} \eta_y$$

$$= z_{\psi} (2y) + z_{\eta} (-2y)$$

$$z_y = 2y (z_{\psi} - z_{\eta}) \rightarrow (3)$$

$$z_{xx} = 2(z_{\psi} + z_{\eta}) + 2x (z_{\psi} \psi_x + z_{\eta} \eta_x \\ + z_{\eta} \psi_x + z_{\eta} \eta_x)$$

$$= 2(z_{\psi} + z_{\eta}) + 2x \left[2z_{\psi} \psi_x + z_{\psi} \eta_x + z_{\eta} \psi_x + z_{\eta} \eta_x \right]$$

$$z_{xx} = 2(z_{\psi} + z_{\eta}) + 4x^2 (z_{\psi} \psi_x + z_{\eta} \eta_x) \rightarrow (4)$$

likewise

$$z_{yy} = 2(z_{\psi} - z_{\eta}) + 4y^2 (z_{\psi} \eta_y - z_{\eta} \psi_y) \rightarrow (5)$$

$$z_{\alpha} = 2\alpha (z_{44} + z_{n2}) \quad (36)$$

$$z_{2\alpha y} = 2\alpha [z_{44}^{4\alpha y} + z_{4n}^{n\alpha y} + z_{n2}^{2\alpha y} + z_{nn}^{n\alpha y}]$$

$$= 2\alpha [z_{44}^{4\alpha y} + z_{4n}^{n\alpha y} + z_{n2}^{2\alpha y} + z_{nn}^{n\alpha y}]$$

$$z_{2\alpha y} = 4\alpha y [z_{44} - z_{nn}] \rightarrow (6)$$

Substitute (2), (3), (4), (5) & (6) in (1) we get

$$\begin{aligned} y^2 [2(z_{44} + z_{nn}) + 4\alpha^2 (z_{44} + 2z_{4n} + z_{nn})] - \\ 2\alpha y [4\alpha y (z_{44} - z_{nn})] + \alpha^2 [2(z_{44} - z_{nn}) + \\ 4y^2 (z_{44} - 2z_{4n} + z_{nn})] = \frac{y^2}{\alpha} [2\alpha (z_{44} + z_{nn})] \\ - \frac{\alpha^2}{y} [2y (z_{44} - z_{nn})] \end{aligned}$$

$$\left. \begin{aligned} z_{44} & [4\alpha^2 y^2 - 8\alpha^2 y^2 + 4\alpha^2 y^2] + \\ z_{4n} & [8\alpha^2 y^2 - 8\alpha^2 y^2] + z_{nn} [4\alpha^2 y^2 + 8\alpha^2 y^2 + 4\alpha^2 y^2] \end{aligned} \right\} = 0$$

$$16\alpha^2 y^2 z_{nn} = 0$$

$$\Rightarrow z_{nn} = 0$$

$$\frac{\partial^2 z}{\partial n^2} = 0$$

$$\Rightarrow \frac{\partial z}{\partial n} = \text{constant}$$

$$\frac{\partial z}{\partial \eta} = A \quad (37)$$

$\Rightarrow z = A\eta + B$ where A and B are arbitrary functions of ξ .

$$z = \eta A(\xi) + B(\xi)$$

(we have $\xi = x^2 + y^2$ and $\eta = x^2 - y^2$)

$$\therefore z = (x^2 - y^2) A(x^2 + y^2) + B(x^2 + y^2)$$

which is the required solution of (1).

Example - 2.4.2 :-

Reduce the equation

$$(n-1)^2 \frac{\partial^2 z}{\partial x^2} - y^{2n} \frac{\partial^2 z}{\partial y^2} = ny^{2n-1} \frac{\partial z}{\partial y} \text{ to}$$

canonical form and find its general solution.

Solution:-

Given equation is

$$(n-1)^2 \frac{\partial^2 z}{\partial x^2} - y^{2n} \frac{\partial^2 z}{\partial y^2} = ny^{2n-1} \frac{\partial z}{\partial y} \rightarrow (1)$$

$$\text{Here } R = (n-1)^2, S = 0, T = -y^{2n}$$

Now

$$\begin{aligned} S^2 - HRT &= 0 + 4(n-1)^2 y^{2n} \\ &= [2(n-1)y^n]^2 > 0 \end{aligned}$$

$$S^2 - HRT > 0$$

\therefore The given PDE is hyperbolic.

$$\text{Now } R\lambda^2 + S\lambda + T = 0$$

$$\Rightarrow (n-1)^2 \lambda^2 - y^{2n} = 0$$

$$\Rightarrow \lambda^2 = \frac{y^n}{(n-1)^2} \quad (38)$$

$$\Rightarrow \lambda = \pm \frac{y^n}{(n-1)}$$

\therefore We have

$$\frac{dy}{d\alpha} \pm \lambda = 0$$

$$\Rightarrow \frac{dy}{d\alpha} \pm \frac{y^n}{(n-1)} = 0$$

$$\Rightarrow (n-1) dy \pm y^n d\alpha = 0$$

$$\Rightarrow \frac{(n-1)}{y^n} dy \pm d\alpha = 0$$

$$\Rightarrow (n-1) y^{-n} dy \pm d\alpha = 0$$

$$\Rightarrow \pm d\alpha = -(n-1) y^{-n} dy$$

$$d\alpha \pm y^{1-n} = \text{constant}$$

$$\therefore \ell_\alpha = d\alpha + y^{1-n}, \quad \eta_\alpha = d\alpha - y^{1-n}$$

$$\text{Now } \ell_{y\alpha} = 1 \quad \mid \quad \eta_{y\alpha} = 1$$

$$\begin{array}{l|l} \ell_y = (1-n)y^{-n} & \eta_y = -(1-n)y^{-n} \\ \ell_y = (1-n)y & \end{array}$$

$$\text{Now } z_\alpha = z_{\ell_\alpha} \ell_{y\alpha} + z_{\eta_\alpha} \eta_{y\alpha}$$

$$z_\alpha = z_{\ell_\alpha} + z_{\eta_\alpha} \rightarrow (2)$$

$$z_y = z_{\ell_\alpha} \ell_{y\alpha} + z_{\eta_\alpha} \eta_{y\alpha}$$

$$= z_{\ell_\alpha} (1-n) y^{-n} + z_{\eta_\alpha} [-(1-n)y]$$

$$z_y = (1-n) y^{-n} [z_{\ell_\alpha} - z_{\eta_\alpha}] \rightarrow (3)$$

$$Z_{xx} = Z_{q4} q_x + Z_{q2} \eta_x + Z_{n4} q_{2x} + Z_{nn} \eta_{2x} \quad (39)$$

$$Z_{xx} = Z_{q4} + 2Z_{q2} + Z_{nn} \rightarrow (4)$$

$$\begin{aligned} Z_{yy} &= (1-n)(-n)y^{-n-1} \cdot (z_q - z_n) + \\ &\quad (1-n)y^{-n} [z_{q4} q_y + Z_{q2} \eta_y - \\ &\quad Z_{n4} q_y - Z_{nn} \eta_y] \\ &= -n(1-n)y^{-n-1} (z_q - z_n) + \\ &\quad (1-n)y^{-n} [z_{q4} (1-n)y^{-n} + \\ &\quad Z_{q2} (-1-n)y^{-n}) - Z_{n4} (1-n)y^{-n} - \\ &\quad Z_{nn} (-1-n)y^{-n}] \end{aligned}$$

$$\begin{aligned} Z_{yy} &= -n(1-n)y^{-n-1} (z_q - z_n) + \\ &\quad (1-n)^2 y^{-2n} [z_{q4} - 2z_{q2} + Z_{nn}] \end{aligned} \rightarrow (5)$$

Substituting (2), (3), (4) and (5) in (1) we get

$$\begin{aligned} &(n-1)^2 [z_{q4} + 2z_{q2} + Z_{nn}] - \\ &y^{2n} [-n(1-n)y^{-n-1} (z_q - z_n) + \\ &(1-n)^2 y^{2n} (z_q - 2z_{q2} + Z_{nn})] \\ &+ ny^{2n-1} [z_{q4} (1-n)y^{-n} (z_q - z_n)] \end{aligned}$$

$$\left. \begin{aligned} z_{44} & [(n-1)^2 - (n-1)^2] + \\ z_{4n} & [2(n-1)^2 + 2(1-n)^2] + \\ z_{nn} & [(n-1)^2 - (1-n)^2] \end{aligned} \right\} = 0 \quad (10)$$

$$\Rightarrow 4(n-1)^2 z_{4n} = 0$$

$$\Rightarrow z_{4n} = 0$$

$$\Rightarrow z = f_1(4) + f_2(n)$$

$$z = f_1(x+y^{1-n}) + f_2(x-y^{1-n})$$

Where f_1 and f_2 are arbitrary functions of their respective arguments.

Section - 2.5

Adjoint Operators :-

Let $Lu = \phi \rightarrow (1)$ where L is the differential operator given by

$$L = a_0(x) \frac{d^n}{dx^n} + a_1(x) \frac{d^{n-1}}{dx^{n-1}} + \dots + a_n(x)$$

The way of introducing the adjoint differential operator L^* associated with L is to form the product vLu and integrate it over the interval of intor

$$\text{Let } \int_A^B vLu dx = \left[\dots \right]_A^B + \int_A^B u L^* v dx \quad (2)$$

which is obtained after repeated integration by parts. (1.1)

Here L^* is the operator adjoint to L , where the functions u and v are completely arbitrary except that Lu and L^*v should exist.

Definition: If $L = L^*$, then L is

If the operator $L = L^*$, then L is called a self adjoint operator.

Example - 2.5.1 :-

If L is the operator

$$R \frac{\partial^2}{\partial x^2} + S \frac{\partial^2}{\partial xy} + T \frac{\partial^2}{\partial y^2} + P \frac{\partial}{\partial x} + Q \frac{\partial}{\partial y} + z \quad \rightarrow (1)$$

and M is the adjoint operator defined by

$$M\omega = \frac{\partial^2}{\partial x^2}(R\omega) + \frac{\partial^2}{\partial xy}(S\omega) + \frac{\partial^2}{\partial y^2}(T\omega)$$

$$- \frac{\partial}{\partial x}(P\omega) - \frac{\partial}{\partial y}(Q\omega) + zw \quad \rightarrow (2)$$

then shows that

$$\iint (\omega Lz - z M\omega) dx dy = \int [u \cos(\theta, y) + v \sin(\theta, y)] ds$$

where c is the closed curve enclosing an area S and

where C is the closed curve (4)

$$U = R\omega \frac{\partial z}{\partial x} - z \frac{\partial}{\partial x}(R\omega) - z \frac{\partial}{\partial y}(S\omega) + P_z \rightarrow (3)$$

$$V = S\omega \frac{\partial z}{\partial x} + T\omega \frac{\partial z}{\partial x} - z \frac{\partial}{\partial y}(T\omega) + Q_z \omega \rightarrow (4)$$

$$\text{If } R_x + \frac{1}{2} S_y = P, \frac{1}{2} S_x + T_y = Q$$

Show that the operator L is self adjoint

Solution :-

$$\omega Lz - z M\omega = \omega \left[R \frac{\partial^2 z}{\partial x^2} + S \frac{\partial^2 z}{\partial x \partial y} + T \frac{\partial^2 z}{\partial y^2} + P \frac{\partial z}{\partial x} + Q \frac{\partial z}{\partial y} + Zz \right] - z \left[\frac{\partial^2}{\partial x^2}(R\omega) + \frac{\partial^2}{\partial x \partial y}(S\omega) + \frac{\partial^2}{\partial y^2}(T\omega) - \frac{\partial}{\partial x}(P\omega) - \frac{\partial}{\partial y}(Q\omega) + Z\omega \right]$$

$$\omega Lz - z M\omega = \left[\omega R \frac{\partial^2 z}{\partial x^2} - z \frac{\partial^2}{\partial x^2}(R\omega) \right] +$$

$$\left[\omega S \frac{\partial^2 z}{\partial y \partial x} - z \frac{\partial^2}{\partial y \partial x}(S\omega) \right] +$$

$$\left[\omega T \frac{\partial^2 z}{\partial y^2} - z \frac{\partial^2}{\partial y^2}(T\omega) \right] +$$

$$\left[\omega P \frac{\partial z}{\partial x} + z \frac{\partial}{\partial x}(P\omega) \right] +$$

$$\left[\omega Q \frac{\partial z}{\partial y} + z \frac{\partial}{\partial y}(Q\omega) \right] + Zz\omega - zZ\omega$$

$$\begin{aligned}
 &= \frac{\partial}{\partial x} \left(\omega R \frac{\partial z}{\partial x} \right) - \frac{\partial}{\partial x} \left(z \frac{\partial}{\partial x} (R\omega) \right) + \\
 &\quad \frac{\partial}{\partial y} \left(s\omega \frac{\partial z}{\partial x} \right) - \frac{\partial}{\partial x} \left(z \frac{\partial}{\partial y} (s\omega) \right) + \\
 &\quad \frac{\partial}{\partial y} \left(T\omega \frac{\partial z}{\partial y} \right) - \frac{\partial}{\partial y} \left(z \frac{\partial}{\partial y} (T\omega) \right) + \\
 &\quad \frac{\partial}{\partial x} (P\omega z) + \frac{\partial}{\partial y} (Q\omega z).
 \end{aligned}$$

$$\begin{aligned}
 \omega Lz - z M\omega &= \frac{\partial}{\partial x} \left[\omega R \frac{\partial z}{\partial x} - z \frac{\partial}{\partial x} (R\omega) - \right. \\
 &\quad \left. z \frac{\partial}{\partial y} (s\omega) + P\omega z \right] + \frac{\partial}{\partial y} \left[s\omega \frac{\partial z}{\partial x} + \right. \\
 &\quad \left. T\omega \frac{\partial z}{\partial y} - z \frac{\partial}{\partial y} (T\omega) + Q\omega z \right]
 \end{aligned}$$

$$\omega Lz - z M\omega = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \text{ where } u$$

and v are given by (3) and (4)

respectively.

$$\begin{aligned}
 \therefore \iint_{S'} (\omega Lz - z M\omega) dx dy &= \iint_S \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) dx dy \\
 &= \int_C (du + dv) ds
 \end{aligned}$$

$$\iint_S (\omega Lz - z M\omega) dx dy = \int_C (u \cos(\theta, \omega) + v \cos(\phi, \omega)) ds$$

which is required result.

Claim :-

(iii)

The operator L is self adjoint

To Prove $L = L^*$

Now,

$$M\omega = \frac{\partial^2 (R\omega)}{\partial x^2} + \frac{\partial^2}{\partial x \partial y} (S\omega) + \frac{\partial^2}{\partial y^2} (T\omega) - \frac{\partial}{\partial x} (P\omega) - \frac{\partial}{\partial y} (Q\omega) + Z\omega$$

$$\begin{aligned} &= R\omega_{xx} + 2R_x\omega_{xy} + R_{yy}\omega + S\omega_{xy} \\ &\quad + Sy\omega_x + S_x\omega_y + \omega S_{xy} + Tw_{yy} \\ &\quad + 2Ty\omega_y + \omega Ty_{yy} - P\omega_{xy} - \omega P_x - Q_y\omega \\ &\quad - Q\omega_y + Z\omega \end{aligned}$$

$$\begin{aligned} M\omega &= R\omega_{xx} + (2R_x + S_y)\omega_{xy} + S_{xy}\omega_{xy} + \\ &\quad T\omega_{yy} - P\omega_{xy} - \omega P_x - Q_y\omega - Q\omega_y + \\ &\quad (2Ty + S_x)\omega_y + R_{yy}\omega + \omega S_{xy} + \\ &\quad \omega Ty_{yy} + Z\omega \end{aligned}$$

Given

$\rightarrow (5)$

$$\left| \begin{array}{l} R_{xy} + \frac{1}{2}S_y = P \\ \Rightarrow 2R_x + S_y = P \end{array} \right| \left| \begin{array}{l} \frac{1}{2}S_{xy} + Ty = Q \\ S_{xy} + 2Ty = 2Q \end{array} \right.$$

Using this in (5) we get

$$\begin{aligned} M\omega &= R\omega_{xx} + 2P\omega_{xy} + S\omega_{xy} + Tw_{yy} - \\ &\quad P\omega_{xy} + \omega P_x - Q_y\omega - Q\omega_y + 2Q\omega_y + \\ &\quad R_{yy}\omega + \omega S_{xy} + \omega Ty_{yy} + Z\omega \end{aligned}$$

$$= R \omega_{xx} + S \omega_{xy} + T \omega_{yy} + P \omega_x + Q \omega_y + \\ Z \omega + R_{xx} \omega + \omega S_{xy} + \omega T_{yy} - \omega P_{x} - Q_y \omega \quad (45)$$

$$= R \frac{\partial^2 \omega}{\partial x^2} + S \frac{\partial^2 \omega}{\partial x \partial y} + T \frac{\partial^2 \omega}{\partial y^2} + P \frac{\partial \omega}{\partial x} + \\ Q \frac{\partial \omega}{\partial y} + Z \omega + \omega \frac{\partial^2 P}{\partial x^2} + \omega \frac{\partial^2 S}{\partial x \partial y} + \\ \omega \frac{\partial^2 T}{\partial y^2} - \omega \frac{\partial P}{\partial x} - \omega \frac{\partial Q}{\partial y}$$

$\Rightarrow L = L^*$ and hence the operator
is self adjoint.

Note:-

The general procedure for
constructing the adjoint of a
differential operator is

- i) Put all the coefficients inside
the derivatives.
- ii) Switch the signs of all odd-
order derivatives.

Example - 2.5.8. Construct the
adjoint to the
laplace operator given by $L(u) = u_{xx} + u_{yy}$.

Solution:-

$$\text{Here } L(u) = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}$$

We know that

$$L = R \frac{\partial^2}{\partial x^2} + S \frac{\partial^2}{\partial x \partial y} + T \frac{\partial^2}{\partial y^2} + P \frac{\partial}{\partial x} + Q \frac{\partial}{\partial y} + z$$

\therefore we get $R=1, S=0, T=1, P=0, Q=0, z=0$

\therefore The adjoint operator to L is defined

by

$$L^* \omega = \frac{\partial^2}{\partial x^2} (R\omega) + \frac{\partial^2}{\partial x \partial y} (S\omega) + \frac{\partial^2}{\partial y^2} (T\omega) -$$

$$-\frac{\partial}{\partial x} (P\omega) - \frac{\partial}{\partial y} (Q\omega) + z\omega$$

$$= \frac{\partial^2 \omega}{\partial x^2} + \frac{\partial^2 \omega}{\partial y^2}$$

$$L^* \omega = \omega_{xx} + \omega_{yy}, \text{ therefore } L^* \omega = \omega$$

$$L^* u = u_{xx} + u_{yy} = L(u)$$

$$\Rightarrow L^* = L$$

Hence the laplace operator is a self adjoint operator.

2.5.1. Riemann's Method

Riemann's method is a way of solving linear hyperbolic equations that are stated in canonical form.

We know that any linear hyperbolic PDE can be written in the form:

$$L(z) = \frac{\partial^2 z}{\partial x \partial y} + a \frac{\partial z}{\partial x} + b \frac{\partial z}{\partial y} + cz = f(x, y) \quad (1)$$

where a, b and c are function of x and y . We define the adjoint of the differential operator L in (1) by

$$M\omega = L^*(\omega) = \frac{\partial^2 \omega}{\partial x \partial y} - \frac{\partial}{\partial x} (a\omega) - \frac{\partial}{\partial y} (b\omega) + c\omega \quad (2)$$

Now

$$\omega L(z) - z M(\omega) = \omega \left[\frac{\partial^2 z}{\partial x \partial y} + a \frac{\partial z}{\partial x} + b \frac{\partial z}{\partial y} + cz \right] - z \left[\frac{\partial^2 \omega}{\partial x \partial y} - \frac{\partial}{\partial x} (a\omega) - \frac{\partial}{\partial y} (b\omega) + c\omega \right]$$

$$\begin{aligned} \omega L(z) - z M(\omega) &= \omega \frac{\partial^2 z}{\partial x \partial y} + \omega a \frac{\partial z}{\partial x} + \omega b \frac{\partial z}{\partial y} + \omega c z - \\ &\quad z \frac{\partial^2 \omega}{\partial x \partial y} + z \frac{\partial}{\partial x} (a\omega) + z \frac{\partial}{\partial y} (b\omega) - z c\omega \end{aligned}$$

$$\begin{aligned} \omega L(z) - z M(\omega) &= \omega \frac{\partial^2 z}{\partial x \partial y} + \omega a \frac{\partial z}{\partial x} + z \frac{\partial}{\partial x} (a\omega) \\ &\quad - z \frac{\partial^2 \omega}{\partial x \partial y} + \omega b \frac{\partial z}{\partial y} + z \frac{\partial}{\partial y} (b\omega) \end{aligned} \quad \rightarrow (3)$$

Now

$$\frac{\partial}{\partial x} (a\omega z) = \omega a \frac{\partial z}{\partial x} + z \frac{\partial}{\partial x} (a\omega) \text{ and } \quad \left. \begin{array}{l} \dots \\ \dots \end{array} \right\}$$

$$\frac{\partial}{\partial y} (b\omega z) = \omega b \frac{\partial z}{\partial y} + z \frac{\partial}{\partial y} (b\omega) \quad \rightarrow (4)$$

Using (4) in (3) we get (4.8)

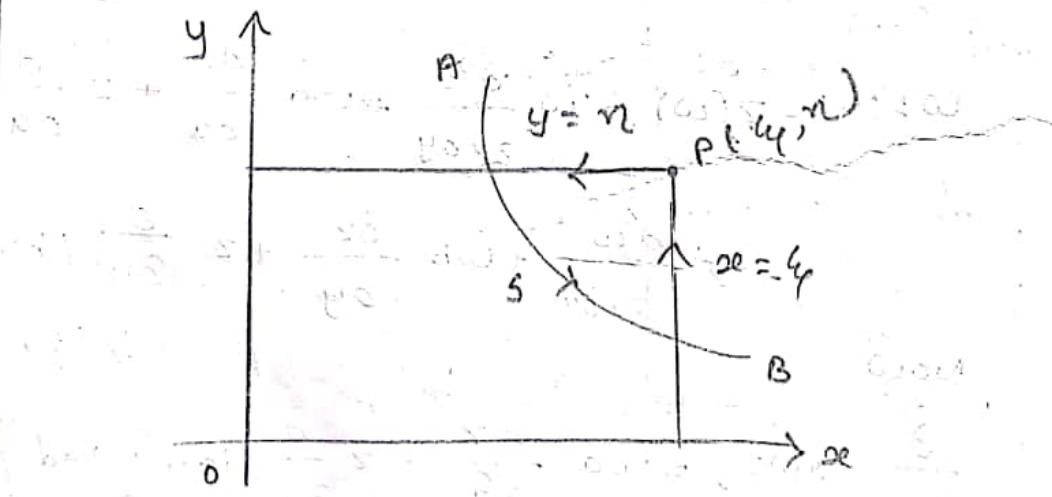
$$\begin{aligned}\omega_L(z) - zM(\omega) &= \omega \frac{\partial^2 z}{\partial x \partial y} + \frac{\partial}{\partial x} (\omega z) - \\ &\quad z \frac{\partial^2 \omega}{\partial x \partial y} + \frac{\partial}{\partial y} (b\omega z) \\ &= \frac{\partial}{\partial x} \left[\omega z - z \frac{\partial \omega}{\partial y} \right] + \frac{\partial}{\partial y} \left[b\omega z + \omega \frac{\partial z}{\partial x} \right]\end{aligned}$$

$$\omega_L(z) - zM(\omega) = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \text{ where}$$

$$\left. \begin{aligned} u &= \omega z - z \frac{\partial \omega}{\partial y} \\ v &= b\omega z + \omega \frac{\partial z}{\partial x} \end{aligned} \right\} \rightarrow (5)$$

Now consider an arc AB of a curve

Γ where PA is parallel to x -axis PB is parallel to y -axis and $P(4, n)$ is any point.



Let S denote the area enclosed by the contour ABPA.

Clearly on AP, $y = \eta$, $dy = 0$ and on PB, $x = b$, $dx = 0$. (49)

By Green's theorem

$$\iint_S (\omega_L(\omega z) - z M(\omega)) dx dy = \iint_S \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) dx dy$$

$= \int_C u dy - v dx$ where C is the closed

contour ABPA.

$$\therefore \iint_S (\omega_L(z) - z M(\omega)) dx dy = \int_C u dy - v dx$$

$$= \int_A^B (u dy - v dx) + \int_B^P (u dy - v dx) + \int_P^A (u dx - v dy)$$

$$\iint_S \omega_L z - z M(\omega) dx dy = \int_A^B (u dy - v dx) + \int_B^P (u dy - v dx) - \int_P^A v dx \rightarrow (b)$$

Now

$$\int_P^A v dx = \int_P^A \left(\omega b z + \omega \frac{\partial z}{\partial x} \right) dx$$

$$= \int_P^A \left(\omega b z + \omega \frac{\partial z}{\partial x} + z \frac{\partial \omega}{\partial x} - z \frac{\partial \omega}{\partial x} \right) dx$$

$$= \int_P^A \left[\left(\omega b z - z \frac{\partial \omega}{\partial x} \right) + \left[\frac{\partial}{\partial x} (\omega z) \right] \right] dx$$

$$\int v dx = \int \left[\frac{\partial}{\partial x} (\omega z) \right] dx + \int z \left(wb - \frac{\partial \omega}{\partial x} \right) dx \quad (50)$$

$$= [\omega z]_P^A + \int_P^A z \left(wb - \frac{\partial \omega}{\partial x} \right) dx$$

$$\int v dx = (\omega z)_A - (\omega z)_P + \int_P^A z \left(wb - \frac{\partial \omega}{\partial x} \right) dx$$

$$\therefore (\omega z)_P = (\omega z)_A + \int_P^A z \left(wb - \frac{\partial \omega}{\partial x} \right) dx - \int v dx \quad (71)$$

Using (6) in (7) we get

$$[\omega z]_P = (\omega z)_A + \int_P^A z \left(wb - \frac{\partial \omega}{\partial x} \right) dx - [udy]_{LB} \quad (71)$$

$$\int_A^B (udy - vdx) + \iint_S (wL(z) - zM(\omega)) dx dy$$

$$= (\omega z)_A + \int_P^A z \left(wb - \frac{\partial \omega}{\partial x} \right) dx - \int_B^P (waz - z \frac{\partial \omega}{\partial y}) dy$$

$$- \int_A^B (waz - z \frac{\partial \omega}{\partial y}) dy - \left(wbz + \omega \frac{\partial z}{\partial x} \right) dx +$$

$$\iint_S [wL(z) - zM(\omega)] dx dy$$

$$[\omega z]_P = (\omega z)_A + \int_P^A z \left(wb - \frac{\partial \omega}{\partial x} \right) dx -$$

$$\int_B^P z \left(wa - \frac{\partial \omega}{\partial y} \right) dy - \int_B^P wiz (ady - bdx) +$$

$$\int_A^B \left(z \frac{\partial \omega}{\partial y} dy + \omega \frac{\partial z}{\partial x} dx \right) + \iint_C [wL(z) - zM(\omega)] dy dx$$

This function w is quite arbitrary, we can choose w to satisfy the following conditions.

$$\text{i)} M(w) = 0 \quad \text{ii)} \frac{\partial w}{\partial y} = aw, \text{ on } x = b$$

$$\text{iii)} \frac{\partial w}{\partial x} = bw, \text{ on } y = n. \text{ iv)} [w]_P = 1.$$

$$\text{Then } [z_P] = [wz]_A + \int_A^P z(wb - bw) dx -$$

$$\int_B^P z(wa - aw) dy - \int_A^B wz(ady - bdx) +$$

$$\int_A^B \left(z \frac{\partial w}{\partial y} dy + w \frac{\partial z}{\partial x} dx \right) + \iint_S (wf(x, y) - zx_0) dy dx$$

$$[z_P] = [wz]_A - \int_A^B wz(ady - bdx) + \int_A^B \left(z \frac{\partial w}{\partial y} dy \right)$$

$$+ w \left(\frac{\partial z}{\partial x} dx \right) + \iint_S wf(x, y) dy dx$$

$\rightarrow (a)$.

This gives the value of z at any point $P(b, n)$, when the values of z and $\frac{\partial z}{\partial x}$ are given on the curve AB .

However, if the values of x , $\frac{\partial z}{\partial y}$

are given, then

$$\int_A^B \left[z \frac{\partial \omega}{\partial y} dy + \omega \frac{\partial z}{\partial x} dx \right] = \int_A^B \left[\frac{\partial}{\partial y} (z\omega) - \omega \frac{\partial z}{\partial y} \right] dy$$

$$+ \int_A^B \left[\frac{\partial}{\partial x} (\omega z) - z \frac{\partial \omega}{\partial x} \right] dx$$

$$= \int_A^B \left[\frac{\partial}{\partial y} (\omega z) dy + \frac{\partial}{\partial x} (\omega z) dx \right] - \int_A^B \left[\omega \frac{\partial z}{\partial y} dy + z \frac{\partial \omega}{\partial x} dx \right]$$

$$= [\omega z]_A^B - \int_A^B \left[z \frac{\partial \omega}{\partial x} dx + \omega \frac{\partial z}{\partial y} dy \right]$$

$$\int_A^B \left[z \frac{\partial \omega}{\partial y} dy + \omega \frac{\partial z}{\partial x} dx \right] = [\omega z]_A^B - \int_A^B \left[z \frac{\partial \omega}{\partial x} dx + \omega \frac{\partial z}{\partial y} dy \right]$$

→ (10)

$$= [\omega z]_B - [\omega z]_A - \int_A^B \left[z \frac{\partial \omega}{\partial x} dx + \omega \frac{\partial z}{\partial y} dy \right]$$

→ (10)

Put (10) in equation (9) we get

$$[z_p] = [\omega z]_A - \int_A^B \omega z (ady - bdx) + [\omega z]_B - [\omega z]_A -$$

$$\int_A^B \left[z \frac{\partial \omega}{\partial x} dx + \omega \frac{\partial z}{\partial y} dy \right] + \iint_S \omega f(x, y) dxdy$$

$$[z_p] = [\omega z]_B - \int_A^B \omega z (ady - bdx) -$$

$$\int_A^B \left(z \frac{\partial \omega}{\partial x} dx + \omega \frac{\partial z}{\partial y} dy \right) + \iint_S \omega f(x, y) dxdy$$

→ (11)

Adding (9) and (11) we get (53)

$$\begin{aligned}
 2[z_p] &= [wz]_A + [wz]_B - 2 \int_A^B wz(\alpha dy - b dx) + \\
 &\quad \int_A^B \left(z \frac{\partial w}{\partial y} dy + w \frac{\partial z}{\partial x} dx \right) - \int_A^B \left(z \frac{\partial w}{\partial x} dx + w \frac{\partial z}{\partial y} dy \right) \\
 &\quad + \iint_S w f(x, y) dx dy \\
 &= [wz]_A + [wz]_B - 2 \int_A^B wz(\alpha dy - b dx) + \\
 &\quad \int_A^B w \left(\frac{\partial z}{\partial x} dx - \frac{\partial z}{\partial y} dy \right) + \int_B^A z \left(\frac{\partial w}{\partial y} dy - \frac{\partial w}{\partial x} dx \right) \\
 &\quad + \iint_S w f(x, y) dx dy
 \end{aligned}$$

$$\begin{aligned}
 [z_p] &= \frac{[wz]_A + [wz]_B - \int_A^B wz(\alpha dy - b dx)}{2} - \\
 &\quad - \frac{1}{2} \int_A^B w \left(\frac{\partial z}{\partial y} dy - \frac{\partial z}{\partial x} dx \right) - \frac{1}{2} \int_A^B z \left(\frac{\partial w}{\partial y} dy - \frac{\partial w}{\partial x} dx \right) \\
 &\quad + \iint_S w f(x, y) dx dy
 \end{aligned}$$

\rightarrow (12)

Equation (11) is used when $z, \frac{\partial z}{\partial y}$ are given on Γ and equation (12) is used when $z, \frac{\partial z}{\partial x}, \frac{\partial z}{\partial y}$ are given on Γ .

Example - 2.5.3:-

Prove that the equation $\frac{\partial^2 z}{\partial x^2} + \frac{1}{4} z = 0$

the Green's function is given by

$w(x, y, \xi, \eta) = J_0 \left\{ \sqrt{(x-\xi)(y-\eta)} \right\}$, where
 $J_0(z)$ is the Bessel function of first kind and of order zero.

Solution:-

The given equation is

$$\frac{\partial^2 z}{\partial x \partial y} + \frac{1}{4} z = 0 \rightarrow (1)$$

$$L(z) = 0 \text{ where } L = \frac{\partial^2}{\partial x \partial y} + \frac{1}{4}.$$

General form is

$$\frac{\partial^2 z}{\partial x \partial y} + a \frac{\partial z}{\partial x} + b \frac{\partial z}{\partial y} + cz = f(x, y) \rightarrow (2)$$

where a, b, c are functions of x & y

$$\text{Here } L = \frac{\partial^2}{\partial x \partial y} + a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y} + c$$

Comparing (1) and (2) we get

$$a=0, b=0, c=1/4, f(x, y)=0.$$

We know:

$$H(w) = \frac{\partial^2 w}{\partial x \partial y} + \frac{\partial}{\partial x}(aw) + \frac{\partial}{\partial y}(bw) + cw$$

put $a=0, b=0, c=1/4$ we get

$$H(w) = \frac{\partial^2 w}{\partial x \partial y} + 0 + 0 + \frac{1}{4}w$$

$$\therefore H = \frac{\partial^2}{\partial x \partial y} + \frac{1}{4}w$$

$$\Rightarrow H = L$$

$$\therefore \omega L(z) - z H(\omega) = \omega \frac{\partial^2 z}{\partial x \partial y} - z \frac{\partial^2 \omega}{\partial x \partial y} \quad (55)$$

$$= \frac{\partial}{\partial x} \left(\omega \frac{\partial z}{\partial y} \right) - \frac{\partial}{\partial y} \left(z \frac{\partial \omega}{\partial x} \right)$$

$$\omega L(z) - z H(\omega) = \frac{\partial \omega}{\partial x} + \frac{\partial v}{\partial y}$$

$$\text{where } U = \omega \frac{\partial z}{\partial y}, V = -z \frac{\partial \omega}{\partial x}$$

$$\therefore \iint_S \omega L(z) - z H(\omega) dxdy = \iint_S \left(\frac{\partial U}{\partial x} + \frac{\partial V}{\partial y} \right) dxdy$$

$$= \int_{ABPA} (U dy - V dx)$$

$$= \int_A^B (U dy - V dx) + \int_B^P U dy - \int_P^A V dx$$

$$= \int_A^B (U dy - V dx) + \int_B^P \omega \frac{\partial z}{\partial y} dy + \int_P^A z \frac{\partial \omega}{\partial x} dx$$

$$\iint_S (\omega L(z) - z H(\omega)) dxdy = \int_A^B (U dy - V dx) +$$

$$\int_B^P \omega \frac{\partial z}{\partial y} dy + \int_P^A z \frac{\partial \omega}{\partial x} dx$$

(1)

$$\text{Now } \int_B^P \omega \frac{\partial z}{\partial y} dy$$

$$\frac{\partial}{\partial y} (\omega z) = \omega \frac{\partial z}{\partial y} + \left(\frac{\partial \omega}{\partial y} \right) z$$

$$\Rightarrow \omega \frac{\partial z}{\partial y} = \frac{\partial}{\partial y} (\omega z) - z \left(\frac{\partial \omega}{\partial y} \right) \quad (56)$$

$$\therefore \int_B^P \omega \frac{\partial z}{\partial y} dy = \int_B^P \left[\frac{\partial}{\partial y} (\omega z) - z \left(\frac{\partial \omega}{\partial y} \right) \right] dy$$

$$\int_B^P \omega \frac{\partial z}{\partial y} dy = [\omega z]_B^P - \int_B^P z \frac{\partial \omega}{\partial y} dy \rightarrow (2)$$

Using (2) in (1) we get

$$\begin{aligned} \iint_S [\omega L(z) - z H(\omega)] dxdy &= \int_B^P (v dy - v dx) + [\omega z]_B^P - \\ &\quad \int_B^P z \frac{\partial \omega}{\partial y} dy + \int_P^A z \frac{\partial \omega}{\partial x} dx \\ &= \int_B^P (v dy - v dx) + [\omega z]_P - [\omega z]_B - \\ &\quad \int_B^A z \frac{\partial \omega}{\partial y} dy + \int_P^A z \frac{\partial \omega}{\partial x} dx \\ \therefore [\omega z]_P &= [\omega z]_B - \int_B^A (v dy - v dx) + \int_B^P z \frac{\partial \omega}{\partial y} dy \\ &\quad - \int_P^A z \frac{\partial \omega}{\partial x} dx + \iint_S [\omega L(z) - z H(\omega)] dxdy \rightarrow (3) \end{aligned}$$

Now suppose that we choose ω in such a way that

$$\text{i)} H(\omega) = 0 \quad \text{ii)} \frac{\partial \omega}{\partial x} = 0 \text{ on } y = \eta$$

$$\text{iii)} \frac{\partial \omega}{\partial y} = 0 \text{ on } x = \eta \quad \text{iv)} [\omega]_P = 1.$$

Let $w = w(f)$, where f is a single valued differentiable function of x and y . (54)

$$\text{Let } f^k = a(x - \xi)(y - \eta), k > 0$$

$$\text{Then } kf^{k-1} \frac{\partial f}{\partial x} = a(y - \eta) \text{ and } \rightarrow (4)$$

$$kf^{k-1} \frac{\partial f}{\partial y} = a(x - \xi) \rightarrow (5)$$

$$\text{Now } w = w(f)$$

$$\frac{\partial w}{\partial x} = \frac{\partial w}{\partial f} \frac{\partial f}{\partial x}$$

$$\frac{\partial w}{\partial x} = \frac{a}{k} (y - \eta) f^{1-k} \frac{dw}{df} \quad [\text{using (5)}]$$

$$\text{To find } \frac{\partial^2 w}{\partial x \partial y}$$

$$\text{Now } \frac{\partial w}{\partial x} = \frac{a}{k} (y - \eta) f^{1-k} \frac{dw}{df}$$

$$\frac{\partial^2 w}{\partial x \partial y} = \frac{a}{k} \left[f^{1-k} \frac{d^2 w}{df^2} + (y - \eta) (1-k) f^{-k} \frac{\partial f}{\partial y} \right]$$

$$\frac{dw}{df} + (y - \eta) f^{1-k} \frac{d^2 w}{df^2} \frac{\partial f}{\partial y}$$

$$\frac{\partial^2 w}{\partial x \partial y} = \frac{a}{k} \left[f^{1-k} \frac{d^2 w}{df^2} + (1-k) f^{-k} \frac{a}{k} (x - \xi) f^{1-k} \right]$$

$$\frac{dw}{df} (y - \eta) + (y - \eta) f^{1-k} \frac{d^2 w}{df^2} \frac{a}{k} (x - \xi) f^{1-k}$$

[using (5)]

$$\frac{\partial^2 w}{\partial x \partial y} = \frac{a}{k} \left[f^{1-k} \frac{d^2 w}{df^2} + (1-k) \frac{1}{k} f^{-k} f^{1-k} \frac{d^2 w}{df^2} + \frac{1}{k} f^{1-k} f^{-k} f^{1-k} f^{1-k} \right]$$

Using $f^k = a(x-\xi)(x-\eta)$

$$\frac{\partial^2 \omega}{\partial x \partial y} = \frac{a}{k} \left[f^{1-k} \frac{dw}{df} + (1-k) \frac{1}{k} f^{1-k} \frac{dw}{df} + \frac{1}{k} \frac{d^2 w}{df^2} f^{2-k} \right] \quad (58)$$

$$= \frac{a}{k} \left[\left(1 + \frac{1}{k} - 1 \right) f^{1-k} \frac{dw}{df} \right] + \frac{a}{k^2} f^{2-k} \frac{d^2 \omega}{df^2}$$

$$\frac{\partial^2 \omega}{\partial x \partial y} = \frac{a}{k^2} f^{1-k} \frac{dw}{df} + \frac{a}{k^2} f^{2-k} \frac{d^2 \omega}{df^2}$$

$$\frac{\partial^2 \omega}{\partial x \partial y} = \frac{a}{k^2} f^{2-k} \frac{d^2 \omega}{df^2} + \frac{a}{k^2} f^{1-k} \frac{dw}{df} \rightarrow (6)$$

Since $H(\omega) = 0$, we get

$$H(\omega) = \frac{\partial^2 \omega}{\partial x \partial y} + \frac{1}{4} \omega = 0 \rightarrow (7)$$

Substitute (6) in (7), we get

$$\frac{a}{k^2} f^{2-k} \frac{d^2 \omega}{df^2} + \frac{a}{k^2} f^{1-k} \frac{dw}{df} + \frac{1}{4} \omega = 0$$

$$\frac{a}{k^2} f^2 \frac{d^2 \omega}{df^2} + \frac{a}{k^2} f \frac{dw}{df} + \frac{1}{4} \omega f^k = 0$$

$$\Rightarrow f^2 \frac{d^2 \omega}{df^2} + f \frac{dw}{df} + \frac{k^2}{4a} \omega f^k = 0$$

This becomes a Bessel's equation
of order zero if we choose $k=0$ and

$$a=1.$$

Then its solution is given by (5a)

$$w(f) = T_0(f) = T_0 \left(\sqrt{(x-q)(y-n)} \right)$$

We see that conditions (i) to (iv) are satisfied. By putting the value of w in eqn (3) and integrating we can find the solution of the given PDE.

Example - 2.5.4 :-

Verify that the Green's function for the equation $\frac{\partial^2 z}{\partial x \partial y} + \frac{2}{x+y} \left(\frac{\partial z}{\partial x} + \frac{\partial z}{\partial y} \right) = 0$

subject to $z=0$, $\frac{\partial z}{\partial x} = 3x^2$ on $y=x$ is given by

$$w(x, y, q, n) = \frac{(x+y)[2xy + (q-n)(x-y) + 2qn]}{(q+n)^3}$$

and obtain the solution in the form

$$w = (x-y) [2x^2 + xy + 2y^2].$$

Solution:-

Given equation is

$$\frac{\partial^2 z}{\partial x \partial y} + \frac{2}{x+y} \left(\frac{\partial z}{\partial x} \right) + \frac{2}{x+y} \left(\frac{\partial z}{\partial y} \right) = 0$$

$$\text{Here } L(z) = \frac{\partial^2 z}{\partial x \partial y} + \frac{2}{x+y} \frac{\partial z}{\partial x} + \frac{2}{x+y} \left(\frac{\partial z}{\partial y} \right) = 0 \rightarrow (1)$$

We know that, the standard canonical form of hyperbolic equation is

$$\frac{\partial^2 z}{\partial x \partial y} + a \frac{\partial z}{\partial x} + b \frac{\partial z}{\partial y} + cz = f(x, y) \quad (60)$$

Comparing (1) and (2), we get

$$a = \frac{2}{x+y}, \quad b = \frac{2}{x+y}, \quad c = 0, \quad f = 0.$$

Adjoint equation of (1) is

$$M(\omega) = 0 \quad \text{where}$$

$$M(\omega) = \frac{\partial^2 \omega}{\partial x \partial y} - \frac{\partial}{\partial x} \left(\frac{\partial \omega}{\partial x} \right) - \frac{\partial}{\partial y} \left(\frac{\partial \omega}{\partial y} \right)$$

Now suppose that we choose ω in such a way that

i) $M(\omega) = 0$ throughout the xy -plane.

ii) $\frac{\partial \omega}{\partial x} = \frac{2}{x+y} \omega$ on $y = n$.

iii) $\frac{\partial \omega}{\partial y} = \frac{2}{x+y} \omega$ on $x = \ell$.

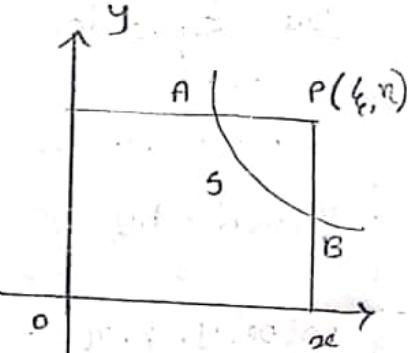
iv) $[\omega]_{P(\ell, n)} = 1$, at $P(\ell, n)$

If we define ω by

$$\omega(x, y, \ell, n) = \frac{(x+y)}{(\ell+n)^3} \left[2xy + (\ell-n)(x-y) + 2\ell n \right]$$

$$\frac{\partial \omega}{\partial x} = \frac{1}{(\ell+n)^3} \left[(x+y)[2y + (\ell-n)] \right] +$$

$$\frac{1}{(\ell+n)^3} \left[(2xy + (\ell-n)(x-y) + 2\ell n)x \right]$$



$$= \frac{1}{(4+y)^3} \left[(x+y)(2y+4-n) + 2xy + (6) \right. \\ \left. (4-n)(x-y) + 2y^2 \right]$$

$$\frac{\partial w}{\partial x} = \frac{1}{(4+y)^3} \left[2y(x+y) + (x+y)(4-n) + \right. \\ \left. 2xy + (4-n)(x-y) + 2y^2 \right]$$

$$\frac{\partial w}{\partial x} = \frac{1}{(4+y)^3} \left[2xy + 2y^2 + (4-n)(x+y+2x-y) \right. \\ \left. + 2xy + 2y^2 \right]$$

$$\frac{\partial w}{\partial x} = \frac{1}{(4+y)^3} \left[4xy + 2y^2 + 2x(4-n) + 2y^2 \right] \rightarrow (3)$$

$$\frac{\partial^2 w}{\partial x \partial y} = \frac{1}{(4+y)^3} \left[4x + 4y + 0 + 0 \right]$$

$$\frac{\partial^2 w}{\partial x \partial y} = \frac{4(x+y)}{(4+y)^3} \rightarrow (4) = (a)$$

$$\frac{\partial w}{\partial y} = \frac{1}{(4+y)^3} \left[(x+y) [2x - (4-n)] + \right.$$

$$\left. \frac{1}{(4+y)^3} [(2xy + (4-n)(x-y)) \times 1] \right]$$

$$\frac{\partial w}{\partial y} = \frac{1}{(4+y)^3} \left[2x(x+y) - (x+y)(4-n) + \right. \\ \left. 2xy + (4-n)(x-y) + 2y^2 \right]$$

$$\frac{1}{(4+y)^3} \left[2x^2 + 2xy + (4-n)[x-y-2x-y] \right. \\ \left. + 2xy + 2y^2 \right]$$

$$\frac{\partial \omega}{\partial y} = \frac{2(4-y)}{(4+y)^3} [4xy + 2x^2 - 2y(4-y) + 2y^2] \rightarrow (5)$$

Now

$$M(\omega) = \frac{\partial^2 \omega}{\partial x \partial y} - \frac{\partial}{\partial x} \left(\frac{\partial \omega}{\partial x+y} \right) + \frac{\partial}{\partial y} \left(\frac{\partial \omega}{\partial x+y} \right)$$

$$M(\omega) = \frac{\partial^2 \omega}{\partial x \partial y} - 2 \left[\frac{(x+y) \frac{\partial \omega}{\partial x} - \omega}{(x+y)^2} \right]$$

$$- 2 \left[\frac{(x+y) \frac{\partial \omega}{\partial y} - \omega}{(x+y)^2} \right]$$

$$= \frac{\partial^2 \omega}{\partial x \partial y} - \frac{2}{(x+y)^2} \left[(x+y) \left[\frac{\partial \omega}{\partial x} + \frac{\partial \omega}{\partial y} \right] \right] + \frac{4\omega}{(x+y)^2}$$

$$M(\omega) = \frac{\partial^2 \omega}{\partial x \partial y} - \frac{2}{x+y} \left[\frac{\partial \omega}{\partial x} + \frac{\partial \omega}{\partial y} \right] + \frac{4\omega}{(x+y)^2} \rightarrow (6)$$

Now

$$\frac{\partial \omega}{\partial x} + \frac{\partial \omega}{\partial y} = \frac{1}{(4+y)^3} [8xy + 2(x^2 + y^2) + 2(4-y)(x-y) + 4y^2]$$

$$= \frac{2(4-y)}{(4+y)^3} [2(4xy) + x^2 + y^2 + (4-y)(x-y) + 2y^2]$$

$$= \frac{2(4-y)}{(4+y)^3} [4xy + x^2 + y^2 + (4-y)(x-y) + 2y^2] \rightarrow (7)$$

Using (4), (7) and we in (6) we get, (63)

$$\begin{aligned}
 M(w) &= \frac{4(x+y)}{(4+y)^3} - \frac{4}{(x+y)^2(4+y)^3} [4xy + x^2 + y^2 + \\
 &\quad (4-y)(x-y) + 24y] + \\
 &\quad \frac{4}{(x+y)^2} \left[\frac{(x+y)[2xy + (4-y)(x-y) + 24y]}{(4+y)^3} \right] \\
 &\quad - \frac{4(x+y)}{(4+y)^3} - \frac{4}{(x+y)^2(4+y)^3} [4xy + x^2 + y^2] \\
 &\quad - \frac{4}{(x+y)^2(4+y)^3} [(4-y)(x-y) + 24y] + \\
 &\quad \frac{4}{(x+y)^2} \left[\frac{(x+y)[2xy + (4-y)(x-y) + 24y]}{(4+y)^3} \right] \\
 M(w) &= \frac{4(x+y)}{(4+y)^3} - \frac{4(x+y)^2}{(x+y)(4+y)^3}
 \end{aligned}$$

$$M(w) = 0$$

\therefore condition (i) is satisfied.

To verify condition (ii)

on $y = n$

$$\left(\frac{\partial w}{\partial x} \right)_{y=n} = \frac{1}{(4+n)^3} [4xn + 2n^2 + 2x^2 - 2x^2 + 24n]$$

$$= \frac{1}{(4+y)^3} [2xy + 2y^2 + 2x^2 + 2y^2] \quad (64)$$

$$\left(\frac{\partial \omega}{\partial x} \right)_{y=y} = \frac{1}{(4+y)^3} [2y^2 + 2x(4+y) + 2y^2] \rightarrow (8)$$

To find $\left(\frac{\partial \omega}{\partial x+y} \right)_{y=y}$

Now $\frac{2}{x+y} \omega = \frac{2}{x+y} \left[\frac{x+y}{(4+y)^3} [2xy + (4-y)(x+y) + 2y^2] \right]$

$$\left(\frac{2\omega}{x+y} \right)_{y=y} = \frac{2}{(4-y)^3} [2ay + (4-y)(x-y) + 2y^2]$$

$$\left(\frac{2}{x+y} \omega \right)_{y=y} = \frac{2}{(4-y)^3} [2ay + \frac{1}{6}x - \frac{1}{6}y - yx + y^2 + 2y^2]$$

$$= \frac{2}{(4-y)^3} [y^2 + 2ay - yx + \frac{1}{6}x + \frac{1}{6}y]$$

$$\left(\frac{2\omega}{x+y} \right)_{y=y} = \frac{2}{(4-y)^3} [y^2 + 2ay + \frac{1}{6}x + \frac{1}{6}y]$$

$$\left(\frac{2\omega}{x+y} \right)_{y=y} = \frac{1}{(4-y)^3} [2y^2 + 2a(x\frac{1}{6}+y) + 2y^2] \rightarrow (9)$$

From (8) and (9), we get

$$\left(\frac{\partial \omega}{\partial x} \right)_{y=y} = \frac{2\omega}{x+y} \text{ at } y=y$$

∴ condition (ii) is verified. (65)

∴ by condition (iii) is verified.

To verify condition (iv)

Now at $x = y$, $y = n$, we have

$$\omega = \frac{(y+n)}{(y+n)^3} [2y^2 + (y-n)(y-n) + 2y^2]$$

$$\omega = \frac{(y+n)}{(y+n)^3} [4y^2 + (y-n)^2]$$

$$\omega = \frac{(y+n)^3}{(y+n)^3} = 1$$

$$[\omega]_P = 1$$

Hence condition (iv) is also satisfied.

Now

$$\omega L(z) - 2H(\omega) = \left[\omega \frac{\partial^2 z}{\partial x \partial y} + \frac{2\omega}{x+y} \left(\frac{\partial z}{\partial x} \right) + \frac{2\omega}{x+y} \left(\frac{\partial z}{\partial y} \right) \right] - \left[2 \frac{\partial^2 \omega}{\partial x \partial y} + 2 \frac{\partial}{\partial x} \left(\frac{2\omega}{x+y} \right) + 2 \frac{\partial}{\partial y} \left(\frac{2\omega}{x+y} \right) \right]$$

$$= \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \quad \text{where}$$

$$M = \frac{\partial z \omega}{\partial y} + 2 \frac{\partial z \omega}{\partial x} \quad \text{and}$$

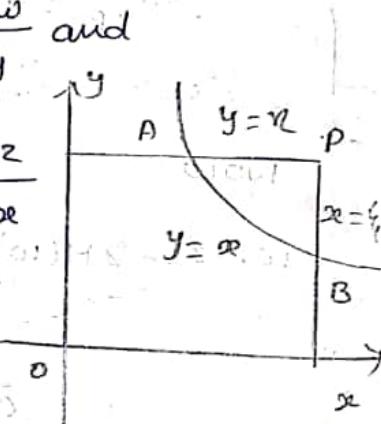
$$N = \frac{\partial z \omega}{\partial x} + \omega \frac{\partial z}{\partial y}$$

$$\begin{aligned}
 \omega L(z) - z M(\omega) &= \omega \frac{\partial^2 z}{\partial x \partial y} - z \frac{\partial^2 \omega}{\partial x \partial y} + \frac{\partial}{\partial x} \left[\frac{2\omega z}{x+y} \right] \\
 &\quad + \frac{\partial}{\partial y} \left[\frac{2\omega z}{x+y} \right] \\
 &= \frac{\partial}{\partial y} \left[\omega \frac{\partial z}{\partial x} \right] - \frac{\partial}{\partial x} \left[z \frac{\partial \omega}{\partial y} \right] + \frac{\partial}{\partial x} \left[\frac{2\omega z}{x+y} \right] \\
 &\quad + \frac{\partial}{\partial y} \left[\frac{2\omega z}{x+y} \right] \\
 &= \frac{\partial}{\partial x} \left[\frac{2\omega z}{x+y} - z \frac{\partial \omega}{\partial y} \right] + \frac{\partial}{\partial y} \left[\frac{2\omega z}{x+y} + \omega \frac{\partial z}{\partial x} \right]
 \end{aligned}$$

$$\omega L(z) - z M(\omega) = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y}$$

where $M = \frac{2z\omega}{x+y} - z \frac{\partial \omega}{\partial y}$ and

$$N = \frac{2z\omega}{x+y} + \omega \frac{\partial z}{\partial x}$$



Now using Green's theorem
we get,

$$\iint (\omega L(z) - z M(\omega)) dx dy = \int (M dy - N dx)$$

$$\begin{aligned}
 &= \int_A^B (M dy - N dx) + \int_B^P (M dy - N dx) + \int_P^C (M dy - N dx) \\
 &\rightarrow (10)
 \end{aligned}$$

which on using condition (i) to (iv)

and the fact that $y = r$ on AP

and $x = l$ on BP

$$y = n \Rightarrow dy = 0 \text{ on AP}$$

(67)

$$dx = 0 \text{ on BP}$$

Equation (10) becomes

$$\begin{aligned} \text{LHS} &= \int_A^P \left[\frac{\partial z \omega}{\partial x + y} - z \frac{\partial \omega}{\partial y} \right] dy - \left[\frac{\partial z \omega}{\partial x + y} + \omega \frac{\partial z}{\partial x} \right] dx \\ &\quad - \int_A^P \left(\frac{\partial z \omega}{\partial x + y} + \omega \frac{\partial z}{\partial x} \right) dx + \int_P^B \left[\frac{\partial z \omega}{\partial x + y} - z \frac{\partial \omega}{\partial y} \right] dy \end{aligned}$$

Now, $\rightarrow (11).$

$$\int_A^P \left(\frac{\partial z \omega}{\partial x + y} + \omega \frac{\partial z}{\partial x} \right) dx = \int_A^P \frac{\partial z \omega}{\partial x + y} dx + (\omega z)_A^P - \int_A^P z \frac{\partial \omega}{\partial x} dx$$

(11) becomes

$$\begin{aligned} \text{LHS} &= \int_A^P \left(\frac{\partial z \omega}{\partial x + y} - z \frac{\partial \omega}{\partial y} \right) dy - \int_B^P \left(\frac{\partial z \omega}{\partial x + y} + \omega \frac{\partial z}{\partial x} \right) dx \\ &\quad - \int_A^P \frac{\partial z \omega}{\partial x + y} dx - (\omega z)_P + (\omega z)_A + \int_A^P z \frac{\partial \omega}{\partial x} dx \\ &\quad + \int_P^B \frac{\partial z \omega}{\partial x + y} dy - \int_P^B z \frac{\partial \omega}{\partial y} dy \end{aligned}$$

Using condition (ii) to (iv) and

$z = 0$ on $y = px$, we get

$$[z]_P = [z \omega]_A - \int_B^A z \frac{\partial \omega}{\partial x} dx$$

Now using the given condition

$$\frac{\partial z}{\partial x} = 3x^2 \text{ on AB, we get } (68)$$

$$\begin{aligned}[z]_P &= [z\omega]_A - \int_B^A \frac{(3x)^2 [2x(2x^2 + 2y^2)]}{(4+y)^3} dx \\ &= \frac{-12}{(4+y)^3} \int (x^5 + x^3 y^2) dx \\ &= \frac{-12}{(4+y)^3} \left[\frac{x^6}{6} + \frac{4y^3}{4} x^4 \right]_4^y \\ &= \frac{-12}{(4+y)^3} \left[\frac{1}{6} (y^6 - 4^6) + \frac{4y^3}{4} (y^4 - 4^4) \right]\end{aligned}$$

$$\begin{aligned}[z]_P &= \frac{-1}{(4+y)^3} [2(y^6 - 4^6) + 3y^2(y^4 - 4^4)] \\ &= \frac{-1}{(4+y)^3} [2[(y^2)^3 - (4^2)^3] + \\ &\quad 3y^2[(y^2)^2 - (4^2)^2]]\end{aligned}$$

$$\begin{aligned}[z]_P &= \frac{4^2 - y^2}{(4+y)^3} [2(4^4 + 4^2 y^2 + y^4) + \\ &\quad 3y^2 8y^2 (4^2 + y^2)] \\ &= (4-y)(24^2 - 4y + 2y^2)\end{aligned}$$

$$\therefore z(x, y) = (x-y)(2x^2 - xy + 2y^2).$$

Hence the result.

- x - .